Mohmoud Mossa

Modeling, Analysis and Enhancement of the performance of a Wind Driven DFIG During steady state and transient conditions



Anchor Academic Publishing

disseminate knowledge

Mossa, Mohmoud A.: Modeling, Analysis and Enhancement of the performance of a Wind Driven DFIG During steady state and transient conditions. Hamburg, Anchor Academic Publishing 2014

Buch-ISBN: 978-3-95489-139-9 PDF-eBook-ISBN: 978-3-95489-639-4 Druck/Herstellung: Anchor Academic Publishing, Hamburg, 2014

Bibliografische Information der Deutschen Nationalbibliothek:

Die Deutsche Nationalbibliothek verzeichnet diese Publikation in der Deutschen Nationalbibliografie; detaillierte bibliografische Daten sind im Internet über http://dnb.d-nb.de abrufbar.

Bibliographical Information of the German National Library:

The German National Library lists this publication in the German National Bibliography. Detailed bibliographic data can be found at: http://dnb.d-nb.de

All rights reserved. This publication may not be reproduced, stored in a retrieval system or transmitted, in any form or by any means, electronic, mechanical, photocopying, recording or otherwise, without the prior permission of the publishers.

Die Informationen in diesem Werk wurden mit Sorgfalt erarbeitet. Dennoch können Fehler nicht vollständig ausgeschlossen werden und die Diplomica Verlag GmbH, die Autoren oder Übersetzer übernehmen keine juristische Verantwortung oder irgendeine Haftung für evtl. verbliebene fehlerhafte Angaben und deren Folgen.

Alle Rechte vorbehalten

© Anchor Academic Publishing, Imprint der Diplomica Verlag GmbH Hermannstal 119k, 22119 Hamburg http://www.diplomica-verlag.de, Hamburg 2014 Printed in Germany

Das Werk einschließlich aller seiner Teile ist urheberrechtlich geschützt. Jede Verwertung außerhalb der Grenzen des Urheberrechtsgesetzes ist ohne Zustimmung des Verlages unzulässig und strafbar. Dies gilt insbesondere für Vervielfältigungen, Übersetzungen, Mikroverfilmungen und die Einspeicherung und Bearbeitung in elektronischen Systemen.

Die Wiedergabe von Gebrauchsnamen, Handelsnamen, Warenbezeichnungen usw. in diesem Werk berechtigt auch ohne besondere Kennzeichnung nicht zu der Annahme, dass solche Namen im Sinne der Warenzeichen- und Markenschutz-Gesetzgebung als frei zu betrachten wären und daher von jedermann benutzt werden dürften.

ACKNOWLEDGMENTS

In the name of Allah, the most Gracious and most Merciful

All deepest thanks are due to ALLAH, the merciful and the compassionate for the uncountable gifts given to me.

I would like to express my great thanks to **Prof. Dr. Ahmed Abd-Al twab hassan**, Professor of Electrical Machines, El Minia University for his discussions and encouragement. I would like to express my deepest thanks to him for his kind supervision, generous advice, clarifying suggestions and support during each step of this work.

I also would like to express my great thanks to **Prof. Dr. Yehia Sayed Mohamed,** Professor of Electrical Machines, EL Minia University for his discussions, advices and encouragement. I would like to express my deepest thanks to him for his kind supervision, generous advice.

I also would like to express my great thanks to **Prof. Dr. Mohamed Mahmoud Hamada,** Professor of electrical power systems, EL Minia University for his discussions and encouragement. I would like to express my deepest thanks to him for his kind supervision, generous advice.

I would like to thank all members and friends in the Electrical Engineering Department, EL Minia University, for their valuable cooperation that was highly needed during the conduction of this study.

I must not forget to express my deepest thanks to my family especially my lovely mother whose prayers, cooperation at all stages of this work and against all odds, have been simply overwhelming.

Mahmoud, 2013

ABSTRACT

Wind electrical power systems are recently getting lot of attention, because they are cost competitive, environmental clean and safe renewable power source, as compared with fossil fuel and nuclear power generation. A special type of induction generator, called a doubly fed induction generator (DFIG), is used extensively for high-power wind applications. They are used more and more in wind turbine applications due to ease controllability, high energy efficiency and improved power quality.

This research aims to develop a method of a field orientation scheme for control both the active and reactive powers of a DFIG driven by a wind turbine. The proposed control system consists of a wind turbine that drives a DFIG connected to the utility grid through AC-DC-AC link. The main control objective is to regulate the dc link voltage for operation at maximum available wind power. This is achieved by controlling the d^e and q^e axes components of voltages and currents for both rotor side and line side converters using PI controllers. The complete dynamic model of the proposed system is described in detail. Computer simulations have been carried out in order to validate the effectiveness of the proposed system during the variation of wind speed. The results prove that, better overall performances are achieved, quick recover from wind speed disturbances in addition to good tracking ability.

Generally, any abnormalities associated with grid asymmetrical faults are going to affect the system performance considerably. During grid faults, unbalanced currents cause negative effects like overheating problems and mechanical stress due to high torque pulsations that can damage the rotor shaft, gearbox or blade assembly. Therefore, the dynamic model of the DFIG, driven by a wind turbine during grid faults has been analyzed and developed using the method of symmetrical components. The dynamic performance of the DFIG during unbalanced grid conditions is analyzed and described in detail using digital simulations.

A novel fault ride-through (FRT) capability is proposed (i.e. the ability of the power system to remain connected to the grid during faults) with suitable control strategy in this research. In this scheme, the input mechanical energy of the wind turbine during grid

faults is stored and utilized at the moment of fault clearance, instead of being dissipated in the resistors of the crowbar circuit as in the existing FRT schemes. Consequently, torque balance between the electrical and mechanical quantities is achieved and hence the rotor speed deviation and electromagnetic torque fluctuations are reduced. This results in a reduction of reactive power requirement and rapid reestablishment of terminal voltage on fault clearance.

Extensive simulation study has been carried out employing MATLAB/SIMULINK software to validate the effectiveness of the proposed system during grid faults. The results demonstrate that the potential capabilities of the proposed scheme in enhancing the performance of DFIG based wind farms to fault ride-through are excellent.

TABLE OF CONTENTS

ACKNOWLED	GMENTS	i
ABSTRACT		ii
TABLE OF CO	NTENTS	iv
LIST OF TABL	ES	vii
LIST OF FIGUE	RES	viii
LIST OF SYMB	OLS	xiv
CHAPTER (1)	INTRODUCTION	1
1-1	General	1
1-2	Research Objectives	3
1-3	Research Outlines	3
CHAPTER (2)	LITERATURE REVIEW	6
2-1	Introduction	6
2-2	Synchronous Generators Driven by a wind	
	Turbine	7
2-2-1	Wound Field Synchronous Generator (WFSG)	
	Driven by a wind turbine	7
2-2-2	Permanent-Magnet Synchronous Generator	
	(PMSG) Driven by a wind turbine	8
2-3	Induction Generators Driven by a variable	
2-3-1	speed wind turbine Squirrel Cage Induction Generator (SCIG)	8
	Driven by a wind turbine	8
2-3-2	Doubly Fed Induction Generator (DFIG) Driven by a wind turbine	10
2-4	Field oriented Control of an Induction machine	11

2-4-1 DFIG	Direct field oriented control of a wind driven	13
2-4-2 DFIG	Indirect field oriented control of a wind driven	14
2-5	Enhancement techniques of DFIG performance	
	during grid faults	15
2-5-1	Traditional techniques for protection of wind	
	turbines during grid faults	16
2-5-2	Crowbar protection technique	16
2-5-2-1	Series antiparallel thyristors LVRT technique	18
CHAPTER (3)	Field Orientation Control of a Wind Driven DFIG Connected to the Grid	21
3-1	Introduction	21
3-2	System description	21 21
3-2	Dynamic modeling of the DFIG	21
3-3-1	Turbine model	22
3-3-2	Induction machine model	24
3-4	DC Link model	24
3-5	Complete system model	25
3-6	Field oriented control of a DFIG	25
3-7	Complete system configuration	27
3-8	Simulation results and discussions	31
CHAPTER (4)	Dynamic Performance of a Wind Driven Doubly Fed Induction Generator During Grid Faults	38
4-1	Introduction	38
4-2	Dynamic Model of a DFIG System	39
4-3	Mathematical Model of DFIG System Under	
	Unbalanced Grid Voltage	40
4-4	System Description	44
4-5	Simulation results and discussions	45

CHAPTER (5)	Enhancement of Fault Ride through Capability of a Wind Driven Doubly Fed Induction	
	Generator Connected to the Grid	62
5-1	Introduction	62
5-2	System under study and proposed FRT scheme	63
5-3	Control strategy of the proposed FRT scheme	64
5-4	Choice of size of storage inductor	65
5-5	Simulation results and discussions	67
CHAPTER (6)	Conclusions and Recommendations	85
6-1	Conclusions	85
6-2	Recommendations for future work	86
REFERENCES	••••••	88
Appendix A		93
Appendix B		94
Appendix C		95

LIST OF TABLES

TABLE	S	Page
3-1	Parameters and data specifications of the DFIG system	31
C.2	Sequence and mode of operation of the FRT scheme	96

LIST OF FIGURES

FIGURES OF CHAPTER (2)		Page
Figure 2-1:	Induction machine (SCIG) based wind turbine	9
Figure 2-2:	Doubly Fed Wound Rotor Induction Generator wind	
	based system	10
Figure 2-3:	General structure of a field oriented control in	
	a synchronous reference frame for an induction machine	12
Figure 2-4:	Structure of a direct field oriented control of a wind	
	driven DFIG	14
Figure 2-5:	Structure of indirect field oriented control of a wind	
	driven DFIG	15
Figure 2-6:	Crowbar circuits. a] Antiparallel thyristor crowbar	
	b] Diode bridge crowbar	17
Figure 2-7:	Series antiparallel thyristors for LVRT	19

FIGURES OF CHAPTER (3)

Figure 3-1:	Doubly-fed induction Generator driven by a wind	
	turbine system	22
Figure 3-2:	Wind turbine control system	23
Figure 3-3:	Power flow through dc-link element	25
Figure 3-4:	Proposed control scheme of the DFIG driven by a wind	
	turbine based on field orientation	30
Figure 3-5:	Performance of the proposed DFIG driven by a wind	
	turbine system with wind speed step change	33
Figure 3-5-a:	Wind speed variation	32
Figure 3-5-b:	Rotor speed variation	32
Figure 3-5-c:	Generated active power	32

Figure 3-5-d:	Generated reactive power	33
Figure 3-5-e:	DC link voltage	33
Figure 3-6:	Dynamic response of the proposed system with	
	sinusoidal variation of wind speed	35
Figure 3-6-a:	Wind speed variation	34
Figure 3-6-b:	Rotor speed variation	34
Figure 3-6-c:	Generated active power	34
Figure 3-6-d:	Generated reactive power	35
Figure 3-6-e:	DC link voltage	35
Figure 3-7:	Performance of the proposed DFIG driven by a wind	
	turbine system with linear bi-directional variation	
	of wind speed	37
Figure 3-7-a:	Wind speed variation	36
Figure 3-7-b:	Rotor speed variation	36
Figure 3-7-c:	Generated active power	36
Figure 3-7-d:	Generated reactive power	37
Figure 3-7-e:	DC link voltage	37

FIGURES OF CHAPTER (4)

Figure 4-1:	Equivalent circuit of a DFIG in the synchronous	
	reference frame rotating at a speed of ω_s	39
Figure 4-2:	Relationships between the $(\alpha$ - $\beta)$ reference frame and the	
Figure 4-3:	$(d - q)^+$ and $(d - q)^-$ reference frames DFIG driven by a wind turbine based on field	41
	orientation control during grid fault conditions	44
Figure 4-4:	performance of the proposed system under a single	

	phase to ground fault during a constant wind speed	49
Figure 4-4-a:	Rotor speed variation	45
Figure 4-4-b:	Generated active power	45
Figure 4-4-c:	Generated reactive power	46
Figure 4-4-d:	DC link voltage	46
Figure 4-4-e:	Mechanical torque	46
Figure 4-4-f:	Electromagnetic torque	47
Figure 4-4-g:	Voltage of phase A	47
Figure 4-4-h:	Voltage of phase B	47
Figure 4-4-i:	Voltage of phase C	48
Figure 4-4-j:	Current of phase A	48
Figure 4-4-k:	Current of phase B	48
Figure 4-4-1:	Current of phase C	49
Figure 4-4-m:	Phase A rotor current	49
Figure 4-5:	performance of the proposed system under a double	
	phase to ground fault during a constant wind speed	55
Figure 4-5-a:	Rotor speed variation	51
Figure 4-5-b:	Generated active power	51
Figure 4-5-c:	Generated reactive power	52
Figure 4-5-d:	DC link voltage	52
Figure 4-5-e:	Mechanical torque	52
Figure 4-5-f:	Electromagnetic torque	53
Figure 4-5-g:	Voltage of phase A	53
Figure 4-5-h:	Voltage of phase B	53
Figure 4-5-i:	Voltage of phase C	54
Figure 4-5-j:	Current of phase A	54
Figure 4-5-k:	Current of phase B	54