5G Radio Access Networks

Centralized RAN, Cloud-RAN, and Virtualization of Small Cells

Edited by Hrishikesh Venkataraman Ramona Trestian



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Preface

In the ever-evolving telecommunication industry, smart mobile computing devices have become increasingly affordable and powerful, leading to a significant growth in the number of advanced mobile users and their bandwidth demands. According to Cisco, high-end devices such as smartphones, iPhones, netbooks, and laptops will account for 24.3 EB per month of data traffic by 2019. In order to achieve this, alternate solutions are required wherein traditional base stations can be replaced by more generic, simple, and small-sized nodes that can carry out minimal tasks such as radiofrequency operations, while moving other computationally intensive tasks such as resource allocation, baseband processing, and so on to a centralized location. In this context, a centralized or cloud radio access network (C-RAN) offers many advantages over a traditional radio access network and the architectural design and techniques offered by C-RAN make it a strong candidate to be incorporated into the 5G wireless network standard. C-RAN would enable joint scheduling and processing between multiple cells, which would eventually enable a collaborative radio environment. Notably, C-RAN would enable a seamless integration between multiple operators and a multiproduct vendor design. On similar lines, small cells have also been looked at, for moving the computation from the user terminal/device to the network; either to the small cell node itself or to the core network. In this regard, the functionality of small cells resembles that offered by the C-RAN. In fact, with the rapid development of network function virtualization (NFV) in the telecommunication world, communication service providers and product vendors have been looking to offer virtualized small cells.

Organization of the Book

Being at a very nascent stage, C-RAN and virtualized small cell technology poses several major research challenges. This book aims to provide a deeper insight into the next generation of RAN architecture; especially in the presence of virtualization and the cloud environment. The book will present a survey of the coexistence of software-defined networking (SDN), C-RAN, and small cell solutions proposed in the literature at different levels, for example, physical characteristics, open access, dynamic resource allocation, technology neutrality, coverage obligations, the minimization of interference problems, and so on.

The book is structured into two main sections. The first section on 5G RAN Architectures and Applications, describes the current challenges in the radio access network environment, which leads to the next generation of wireless networks. It includes important chapters written by researchers from prestigious laboratories in China, the Czech Republic, Germany, Spain, and the United Kingdom, which each present what is currently state of the art in the area of next-generation 5G networks, including possible architectures and solutions, performance evaluation and interference mitigation, resource allocation management, energy efficiency and cloud computing, and so on. The 5G RAN Architectures and Applications section consists of five chapters. The following offers a brief description of each of the chapters in this section:

Chapter 1 discusses a new kind of user-centric network architecture for the next generation of mobile systems (5G), referred to as a Frameless Network Architecture (FNA). The proposed FNA decomposes the functionality of the traditional base station into a centralized processing entity (CPE) and an antenna element (AE), such that the CPE will maintain the networking, implement the signal processing, handle the control plane and user place, manage the radio resources, and construct on-demand user-centric serving sets.

Chapter 2 identifies the need for a distributed architecture in 5G networks for efficient computation management in mobile edge computing. Importantly, it introduces two options for newly distributed deployments of the management unit. The chapter also discusses the integration of the proposed solution into 5G mobile networks based on C-RAN. Through an analysis and simulations of the proposed architectures, we prove that both signaling delay and signaling load could be significantly reduced compared with centralized solutions.

Chapter 3 provides a comprehensive survey of the latest developments and the use of nonorthogonal multiple access (NOMA) schemes for next-generation 5G networks. The survey first provides a comparison between orthogonal multiple access schemes and NOMA schemes, identifying the advantages and disadvantages of each of the technologies. The solutions offered by NOMA schemes for the uplink and downlink transmissions are discussed with an emphasis on the NOMA-based solutions for downlink transmissions.

Chapter 4 looks into the performance evaluation of a NOMA-based mechanism used within the wireless downlink cloud radio access network (WD-CRAN) environment. The mechanism makes use of successive interference cancellation (SIC) receivers in order to enhance the reception and to lay multiple base stations over each other in the power domain.

Chapter 5 begins with a detailed background and terminologies to set a common understanding of cloud computing, toward a flexible networking future. The chapter will detail future network clouds and the need for efficient frameworks for cloud management and control. Furthermore, the chapter will outline OpenStack in order to offer the reader the tools for experimenting.

The second section, entitled 5G RAN Virtualization Solutions, presents various solutions proposed by world-known researchers in different areas of software-defined networks and virtualization. It includes important chapters written by researchers from prestigious laboratories in Belgium, Germany, Greece, India, Italy, and the United Kingdom, presenting results in the areas of software-defined networks, mobility management, the Internet of things (IoT), sensor applications, and so on. The 5G RAN virtualization solutions section consists of six chapters; the following offers a brief description of each of these.

Chapter 6 discusses two enabling technologies for C-RAN that allow decoupling beyond baseband and radio, that is, SDN and NFV. Importantly, the pros and cons of these enabling technologies are thoroughly discussed.

Chapter 7 begins with an introduction on the need for SDN. The new SDN paradigm is then briefly explained and compared with traditional networks. Furthermore, following a bottom-up approach, an in-depth overview of SDN architecture is provided.

Chapter 8 is a detailed chapter that provides a comprehensive yet practical walkthrough for managing the mobility of next-generation wireless networks with SDN.

Chapter 9 provides a detailed description of self-x network management, beginning with autonomic and cognitive networking and then goes on to describe in detail the proposed next-generation self-configurable and self-optimized framework. Chapter 10 discusses different distributed data aggregation mechanisms and compression techniques for the 5G virtual RAN IoT-based sensor applications. It shows the mechanism for combining a centralized C-RAN architecture for the mobile cloud and a cluster head-based architecture for the wireless sensor network. Also, it demonstrates the importance of their approach in two application domains—the *distributed aggregation of temperature measurements* and *distributed video coding of visual data* obtained with wireless visual sensors.

Chapter 11 explains the 5G C-RAN uplink cross-layer optimization mechanism to support massive traffic in sensor network services. Importantly, the chapter investigates and studies the planning difficulties and restrictions that are related to interference, throughput, accessibility, and uplink connectivity, proposing solutions and rules to be followed. Furthermore, it explains why C-RAN planners should fulfill the proposed recommendations when optimizing the 5G IoT's network performance.

The prospective audiences for this book are mainly undergraduate students, postgraduate students, and researchers who are interested in learning more about the latest developments in the areas of mobile and wireless communications. It also targets industry professionals who are working or are interested in this area, providing them with a reference to the latest efforts that advance the research further by addressing some of the shortcomings of the existing solutions.

The editors wish you a pleasant reading.

Hrishikesh Venkataraman

Indian Institute of Information Technology, India

Ramona Trestian Middlesex University, United Kingdom

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In particular, Hrishikesh Venkataraman would like to thank both of his parents for instilling a confidence in learning new topics and the ability to produce the learning in proper form to an audience. Also, he would like to thank his wife and his mother-in-law for their patience and dedication to other aspects of personal life while writing the chapters and editing this book. Importantly, he would like to thank his institution for their support for allowing him to focus on his research and allowing him to write/edit the book.

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Editors

Hrishikesh Venkataraman completed his M.Tech at the Indian Institute of Technology, Kanpur, from 2002 to 2004 and his PhD at Jacobs University, Bremen, Germany, from 2004 to 2007. He was a recipient of the Indo-German DAAD scholarship from 2003 to 2004 and was awarded an Irish national research fellowship from 2008 to 2010. From 2008 to 2013, he was a research fellow, and subsequently, principal investigator (PI) with the Irish national research center, the RINCE Institute, at Dublin City University, Ireland. During this period, he also served as project manager for two research projects at RINCE, funded by Everseen Limited and Ericsson Research, Ireland. In 2013, Dr. Venkataraman returned to India and worked as a technical architect in the Chief Technology Office of Network Technology Unit of Tech Mahindra for two years. Here, he was involved in developing algorithms, building solutions, and made a contribution to ETSI-based consortium in the area of virtualization.

From May 2015 onwards, Dr. Venkataraman has been a professor at Indian Institute of Information Technology, Chittoor, Sricity, leading the vehicular and wireless communication research theme. He is the institute nodal officer for national knowledge networks and also serves as the faculty-in-charge for networks, servers, and information systems. Furthermore, he has filed 2 patents, has more than 50 international publications in different journals of IEEE, ACM, and Springer, and international conferences, including 2 best paper awards; and served as editor of *Transactions on Emerging Telecommunication Technologies*; for 5 years, from April 2011–2016. Also, he has edited two books published by CRC Press and Springer.

Ramona Trestian received her BEng degree in telecommunications from the Electronics, Telecommunications, and Technology of Information Department, Technical University of Cluj-Napoca, Romania in 2007, and her PhD degree from the School of Electronic Engineering, Dublin City University, Dublin, Ireland in 2012 for her research in adaptive multimedia systems and network selection mechanisms. She worked with IBM Research, Dublin as an IBM/IRCSET exascale postdoctoral researcher, from December 2011 to August 2013. She is currently a senior lecturer with the Design Engineering and Mathematics Department, School of Science and Technology, Middlesex University, London, UK. She has published in prestigious international conferences and journals and has edited two books. Her research interests include mobile and wireless communications, multimedia streaming, handover and network selection strategies, and software-defined networks. She is a reviewer for international journals and conferences and a member of the IEEE Young Professionals, IEEE Communications Society, and IEEE Broadcast Technology Society.



Contributors

Giuseppe Araniti is an assistant professor of telecommunications at the University Mediterranea of Reggio Calabria, Italy. From the same university he received his Laureate (2000) and his PhD degree (2004) in electronic engineering. His major area of research includes personal communications systems, enhanced wireless and satellite systems, traffic and radio resource management, multicast and broadcast services, device-to-device and machine-type communications over 4G/5G cellular networks.

Zdenek Becvar received his MSc and PhD in telecommunication engineering from the Czech Technical University in Prague, Czech Republic, in 2005 and 2010, respectively. From 2006 to 2007, he joined Sitronics R&D center in Prague focusing on speech quality in voice-over IP (VoIP). Furthermore, he was involved in the research activities of the Vodafone R&D center at Czech Technical University in Prague in 2009. He was an intern at the Budapest Polytechnic, Hungary (2007), CEA-Leti, France (2013), and EURECOM, France (2016). Now, he is an associate professor at the Department of Telecommunication Engineering, Czech Technical University in Prague, Czech Republic. He has participated in several European and national research projects focused on mobile networks. In 2013, he became a representative of the Czech Technical University in Prague in ETSI and 3GPP standardization organizations. He is a member of more than 15 program committees at international conferences or workshops and he has published 3 book chapters and more than 60 conference or journal papers. He acts as a reviewer for many prestigious journals including journals published by IEEE, Wiley, Elsevier, and Springer. He works on the development of solutions for future mobile networks (5G and beyond) with a special focus on the optimization of radio resource management and mobility support, self-optimization, the architecture of radio access networks, and small cells.

Namadev Bhuvanasundaram received his MSc degree in telecommunications engineering from Middlesex University, London, UK, in 2012 and his BEng in electrical, electronics, and communications engineering from Pondicherry University, Puducherry, India, in 2009. His research interests include mobile and wireless communications, multiple-input multiple-output systems, and multiple access technologies for next-generation networks.

Massimo Condoluci is currently a postdoctoral research associate at the Center for Telecommunications Research, Department of Informatics, King's College London, UK. He received his MSc degree in telecommunications engineering and his PhD in information technology in 2011 and 2016, respectively, from the University Mediterranea of Reggio Calabria, Italy. His main current research interests include softwarization, virtualization, mobility management, and group-oriented and machine-type communications over 5G systems.

Xuan Thuy Dang received his diploma in computer sciences from the Technical University, Berlin, Germany, in 2013. Since then, he has been a research associate at the German-Turkish Advanced Research Centre for information communication technology and a PhD candidate in the future mobile network at DAI-Labor/TU-Berlin. His main research interests include (1) software-defined networking, (2) cloud computing, (3) service-aware agile networks, (4) mobile ad hoc, delay-tolerant, and information-centric networking.

Nikos Deligiannis is an assistant professor with the Electronics and Informatics Department at Vrije Universiteit Brussel (VUB) and principal investigator in data science at the iMinds Institute in Belgium. He is also the codirector of the VUB-Duke-UCL joint lab on big data, together with M. Rodrigues (University College London, UK) and R. Calderbank (Duke University, USA) and the vice director of the Master of Applied Computer Science program at Vrije Universiteit Brussel.

He received a diploma in electrical and computer engineering from the University of Patras, Greece, in 2006, and his PhD in applied sciences (awarded with highest honors and congratulations from the jury) from Vrije Universiteit Brussel, Belgium, in 2012. His research interests include big data mining, processing and analysis, compressed sensing, Internet of things networking, and distributed processing. Professor Deligiannis has authored over 75 journal and conference publications, book chapters, and he holds one US patent (promoted by BAFTA, UK). He was the recipient of the 2011 ACM/IEEE International Conference on Distributed Smart Cameras Best Paper Award and the 2013 Scientific Prize, IBM, Belgium. Professor Deligiannis is a member of the IEEE. From July to September 2013, Professor Deligiannis was the external advisor to the Greek prime minister's cabinet, responsible for consultation on the integration of the Internet of things and big data technologies in the Greek public sector. From October 2013 to February 2015, he was a senior researcher at the Department of Electronic and Electrical Engineering at University College London, UK, and a technical consultant on big visual data technologies at the British Academy of Film and Television Arts (BAFTA), UK. Professor Deligiannis has been consulting companies and startups operating in the area of big data analytics for smart cities.

Manzoor Ahmed Khan received his PhD degree in computer science from the Technical University, Berlin, Germany, in December 2011. Since 2011, he has served as a senior researcher and the vice director of the Competence Center, Network and Mobility at DAI-Labor. He has served in the deployment and optimization departments of a major mobile operator in Pakistan. His main research interests include (i) software-defined networking; (ii) cloud computing; (iii) learning in agent-based autonomic networking; (iv) experimental research focusing on various use cases of long-term evolution (LTE), network virtualization, 5G vision, and LTE protocols and operations; (v) user-centric network selection, resource allocation, and the quality of experience (QoE) in future wireless networks and in distributed cloud computing systems. He received a gold medal and a silver medal for securing highest marks (first position) in his batch for his master's and bachelor's degrees, respectively. He was also the recipient of several best paper awards. Dr. Khan is the author of several scientific publications including conference papers, journal articles, and book chapters.

Joanna Kusznier received her diploma in economics from Humboldt University in Berlin, Germany, in 2013. Her main research interests include cloud computing, autonomous learning, and robotics.

Jiaxiang Liu is currently pursuing his master's degree at the Beijing University of Posts and Telecommunications, China. His current research interests include cache-enabled networks and software-defined networks for 5G.

Felicia Lobillo received an MSc degree in telecommunication engineering from the University of Seville in 1998. She has been involved in system integration projects for telecommunication operators for more than 12 years, which have provided her with a deep knowledge of business support systems in the telecommunications sector and how to implement technology solutions to meet business requirements. She participated in European research and development projects for 4 years in the scope of future networks, dealing with cutting-edge technologies including small cells, the cloud, big data or SDN, and NFV for 5G. During this time, she acquired an overview of the main technology trends that will drive the IT and telecommunication market in the near future. In November 2015, she joined the Business Intelligence and Analytics team in Atos Iberia, where she is focused on developing business opportunities for Atos around big data and analytics.

Spyridon Louvros is assistant professor in the Computer & Informatics Engineering Department, Supreme Technological & Educational Institute of Western Greece in Patras, Greece. He has offered, for more than 10 years, R&D consultancy and training services in Teledrom aktiebolag (AB), an official subcontractor for Ericsson AB. He is also one of the founders of Mobile Cloud and Network Services (MCNS), Cyprus, a telecommunication and cloud services company offering expertise services in big data analysis and models as well as mobile network planning and optimizing. He graduated from the Physics Department, University of Crete, with a specialization (minor field) in applied physics, microelectronics, and lasers. He engaged in postgraduate studies (MSc) in the United Kingdom, Department of Electronic System Design, RF Design & Telecommunications Section of Aviation Electronics, School of Aeronautics & Aerospace Engineering, the University of Cranfield, UK. During his studies, he was awarded a 2-year full scholarship from the Alexandros Onassis Foundation for Postgraduate Studies in Western Europe due to academic excellence. In 2004, he received his PhD diploma from the Signal Processing Laboratory, Section of Electronics & Information Technology, Physics Department, University of Patras, Greece. Dr. Louvros has worked as microwave planning and optimizing engineer in Siemens TELE S.A., and a senior switching engineer in Vodafon Hellas S.A. for the Network Operational & Maintenance Department. He joined Cosmote Cellular Technologies S.A. as a section manager for network statistics and a quality assurance engineer. Dr. Louvros is well experienced in statistical analysis and key performance indicators (KPIs) for live networks and has offered consultancy services in several projects aimed at developing real-time monitoring solutions and expert data-based systems for automatic problem solving. He has participated in national and international research projects and his research interests focus on wireless communications, mobile network and big data analysis and performance, mobile network capacity planning and dimensioning, applied algebraic topology in telecommunication networks, 5G technologies with emphasis on C-RAN and wireless optical communication technologies (LiFi). He holds 75 papers for international conferences and journals, as well as 12 book chapters in international publication, his papers have been cited (more than 100 citations) by international researchers, and he is an active reviewer for international journals. He is a member of the IEEE Society, Hellenic IEEE Communications Chapter, Physics Hellenic Union.

Pavel Mach received his MSc and PhD degrees in telecommunication engineering from the Czech Technical University in Prague, Czech Republic, in 2006 and 2010, respectively.

During his study, he joined research groups at Sintronics and Vodafone R&D centers focusing on wireless mobile technologies. He is a member of more than 15 program committees of international conferences. He has published more than 50 papers in international journals and conferences. He has been actively involved in several national and international projects. He participated in several projects founded by the European Commission. His research interests include cognitive radio, device-to-device communication, and mobile edge computing. He is dealing with aspects relating to radio resource management, such as mobility management, radio resource allocation, and power control in emerging wireless technologies.

Toktam Mahmoodi is currently a lecturer in telecommunications at the Department of Informatics, King's College London. She was a visiting research scientist with F5 Networks, in San Jose, CA, in 2013, a postdoctoral research associate in the intelligent systems and networks research group at the Electrical and Electronic Engineering Department of Imperial College during 2010 and 2011, and a Mobile Virtual Center of Excellence researcher from 2006 to 2009. She worked on European FP7 and EPSRC projects aiming to push the boundaries of next-generation mobile communications forward. She also worked in the mobile and personal communications industry, from 2002 to 2006, and in an R&D team on developing digital enhanced cordless telecommunication standards for wireless local loop applications. She has a BSc degree in electrical engineering from Sharif University of Technology, Iran, and a PhD degree in telecommunications from King's College London, UK.

Huan X. Nguyen received his BSc degree at the Hanoi University of Science and Technology (Vietnam) in 2000. He then pursued his PhD at the University of New South Wales (Australia) during 2003–2006. He has since worked in various posts for several universities in the UK. He is currently a senior lecturer at the School of Science and Technology, Middlesex University (London, UK). His research interests include physical layer security, energy harvesting, multiple-input multiple-output techniques, network coding, relay communication, cognitive radio, and multicarrier systems. Dr Nguyen is a senior member of the IEEE. He is currently serving as editor of the *KSII Transactions on Internet and Information Systems*.

Ngozi Ogbonna received her MSc degree in telecommunications engineering from Middlesex University, London, UK, in 2014 and her BEng from Federal University of Technology Owerri, Nigeria, in 2011. She is currently working as a research and development officer for Concept Nova, Lagos, Nigeria. Her research interests include mobile and wireless communications, cloud radio access networks, and the Internet of things.

Miguel A. Puente received his MSc in telecommunications engineering from the Universidad Politécnica de Madrid (UPM) in 2012. In this period, he also completed an information technology masters' degree at the University of Stuttgart (2010–2012). Since 2012, he has been with Atos Research & Innovation (Spain), where he is involved in European research projects addressing 5G, LTE, cloud computing, mobile cloud/edge computing, QoE/QoS optimization and recursive Internet among other topics. Particularly within the European project TROPIC, he has worked on architectural enhancements of LTE mobile networks to cope with computationally enabled base stations for mobile cloud computing, and cloud orchestration and virtual infrastructure management for mobile edge computing. Since 2014, he has been a PhD candidate at UPM. Matej Rohlik received his MSc and PhD degrees from the Czech Technical University in Prague, Czech Republic, in 2008 and 2012, respectively. His research addresses cybersecurity topics with a focus on the security of the next-generation mobile networks and sensor networks. From 2008 to 2015, he was actively involved in international FP7 projects funded by the European Commission (such as FREEDOM and TROPIC), national projects (funded by the Ministry of the Interior of the Czech Republic and the National Security Authority of the Czech Republic), and contributed to 3rd generation partnership project standardization. From 2014 to 2015, he coordinated the International Telecommunication Union Center of Excellence for Cybersecurity at the Colorado Technical University. He is an innovative, diligent, and highly organized cybersecurity expert with more than 10 years of professional experience in the design, implementation, and management of top-notch, compliant, and cost-effective solutions for global clients spread across the Asia-Pacific, Europe, Middle East, and Africa, and American regions. He has been awarded with internationally recognized certifications, such as the Certified Information Systems Security Professional, Cisco Certified Network Professional, Cisco Certified Design Professional, Cisco Certified Network Associate, and the Security and Cisco Cyber Security Specialist certificates.

Purav Shah is a senior lecturer in the School of Science and Technology at Middlesex University, London. He received his PhD in communication and electronics engineering from the University of Plymouth, UK, in 2008. He worked as an associate research fellow at the University of Exeter on the EU-FP6 PROTEM project on scanning probe-based memories from 2008 to 2010. His work included read channel design, noise modeling, and signal processing for probe storage. His research interests are broadly in the field of the performance evaluation of wireless sensor networks (protocols, routing, and energy efficiency), the Internet of things, and M2M solutions, system modeling of heterogeneous wireless networks, and intelligent transportation systems. He is an active member of the IEEE and a reviewer of the *IET Electronics Letters*, *IEEE Transactions on Circuits and Systems for Video Coding, KSII Transactions on Internet and Information Systems*, MDPI Sensors and International Journal on Communication Systems, Wiley, and *Computer Networks*, Elsevier.

Bolagala Sravya is an undergraduate honors student of computer science at the Indian Institute of Information Technology, focusing on information security and networking. She is in the top 5% of the students in her institute and will be graduating in July 2017.

Zhao Sun is currently pursuing his PhD degree in Beijing University of Posts and Telecommunications, China. He has 5 years of research experience in the area of mobile communication. His current research interests mainly include mobility management in heterogeneous networks and evolved network architecture for 5G.

Tomas Vanek received his MSc and PhD in telecommunication engineering from the Czech Technical University in Prague, Czech Republic, in 2000 and 2008, respectively. He has participated in several European and national research projects focused on security and mobile networks. In 2013, he was an intern at Universidad de Costa Rica. He is currently an assistant professor at the Department of Telecommunication Engineering, Czech Technical University in Prague, Czech Republic. He has published more than 20 conference or journal papers. Since 2014, he has been working as an ICT security consultant in a privately held company with a focus on public key infrastructure systems and authentication processes. He participates in the development of

security solutions for next-generation mobile networks and IoT networks with a special focus on the security of over-the-air update processes.

Quoc-Tuan Vien received his BSc (Hons) degree from Ho Chi Minh City University of Technology, Vietnam, in 2005; his MSc degree from Kyung Hee University, South Korea, in 2009; and his PhD degree from Glasgow Caledonian University, UK, in 2012, all in telecommunications. From 2005 to 2007, he was with Fujikura Fiber Optics Vietnam Company, Binh Duong, Vietnam, as a production system engineer. From 2010 to 2012, he worked as a research and teaching assistant with the School of Engineering and Built Environment, Glasgow Caledonian University. In spring 2013, he worked as a postdoctoral research assistant with the School of Science and Technology, Nottingham Trent University, Nottingham, UK. He is currently a lecturer in computing and communications engineering with the School of Science and Technology, Middlesex University, London, UK. His research interests include multiple-inputmultiple-output, space-time coding, network coding, physical layer security, cross-layer design and optimization, relay networks, cognitive radio networks, heterogeneous networks, and cloud radio access networks. Dr. Vien is a senior member of the IEEE, a member of the Institution of Engineering and Technology, and a fellow of the Higher Education Authority. He is an author of a book, a leading author of 38 papers, and a coauthor of 19 papers published at major conferences and Institute for Scientific Information journals. He is an editor of the International Journal of Big Data Security Intelligence since 2015, an associate editor of the International Journal of Computing and Digital Systems since 2015, a technical symposium co-chair for the IEEE International Conference on Emerging Technologies and Innovative Business for the Transformation of Societies (EmergiTech 2016) and the International Conference on Recent Advances in Signal Processing, Telecommunications and Computing (SigTelCom 2017), a session chair of the IEEE VTC Spring Conference in 2016, the IEEEWCNC and ISWCS Conferences in 2015, and the IEEE VTC Fall Conference in 2014, and a technical program committee member and reviewer of more than 50 conferences and journals since 2011.

Michal Vondra received his BSc degree in electronics and telecommunication engineering and his MSc degree in telecommunication engineering and radioelectronics from Czech Technical University in Prague, in 2008 and 2010, respectively. In 2015, he received his PhD degree in telecommunication engineering from the Czech Technical University in Prague. His thesis, the "Allocation of Resources in Network with Small Cells," earned the Dean's Award for prestigious dissertation thesis. Since 2010, he has continuously participated in FP7 projects founded by the European Commission (FREEDOM, TROPIC) and also in several national projects. From January to June 2014, he was an intern at the Performance Engineering Laboratory at University College Dublin, Ireland, where he cooperated on project TRAFFIC. Currently, he is a visiting researcher at Wireless@KTH where he is cooperating on the Instruments to Remove Confiscated Asset Recovery Obstacles project. He has published more than 15 conference papers, journal papers, and book chapters. His research interests include mobility management in wireless networks and vehicular ad hoc networks, intelligent transportation systems, and direct air-to-ground communication.

Xiaodong Xu received his PhD degrees from Beijing University of Posts and Telecommunications (BUPT), China, in 2007. He is currently an associate professor at BUPT. From January 2014 to January 2015, he worked as a guest researcher at Chalmers University of Technology, Sweden. His research interests cover radio access network architecture, radio resource management, wireless network virtualization, and interference management.

5G RAN ARCHITECTURES AND APPLICATIONS



Chapter 1

Frameless Network Architecture for User-Centric 5G Radio Access Networks

Xiaodong Xu, Zhao Sun, and Jiaxiang Liu

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The system capacity for future mobile communication needs to be increased to fulfill the emerging requirements of mobile services and innumerable applications. For a long time, the cellular

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network topology and networking strategies have been regarded as the most promising way to provide the required capacity increase. However, with the emerging densification of cell deployments, the traditional cellular structure limits resource efficiency, and the coordination between different types of base stations is more complicated and entails heavy cost.

Consequently, this chapter discusses a new kind of user-centric network architecture for the 5th generation mobile system (5G), known as *frameless network architecture* (FNA). As there have been several studies on the network architectural evolution required for 5G, we first make a general introduction about current work.

For FNA, by decomposing the traditional Base Station (BS) into a Centralized Processing Entity (CPE) and Antenna Element (AE), the Radio Access Network (RAN) of FNA consists of two new network elements. The function of the CPE is to maintain the networking, implement the signal processing, handle the Control Plane (CP) and User Plane (UP), manage the radio resources including the connected AEs, and construct an on-demand user-centric serving set for specific users. The AEs are selected to construct a serving set for the specific user according to its quality of service (QoS) requirement.

Based on FNA, each user is always focused as being the coverage center of the serving AE set, which means that the cell boundary or the traditional cellular structure will no longer exist. The CP and UP are separated based on the FNA. The designated controlling AE implements the function of the CPE, which is handling and maintaining the control plane. The Data-AEs maintain their own User Plane under the control of Controlling-AEs.

In addition, based on FNA, the Control Plane and User Plane adaptation strategy is discussed in this chapter to improve the system Energy Efficiency (EE). A three-step system EE optimization with constraints on the CP/UP adaptation is given. We optimize the system EE via CP and UP construction and adaptation while guaranteeing the user QoS. The system-level simulation results show that, with constraints on the QoS of the users, the system EE performances are improved.

Finally, in order to further improve resource efficiency, especially the AE usage efficiency in the coordination-based user-centric RAN, we discuss the routing strategy in FNA. Based on the decoupling of CP and UP, the network virtualization is explored through Software Defined Network (SDN) approaches. We virtualize the wireless resources into a shared Resource Pool. In the User Plane, we use the *flow* to support different service slices. There can be multiple coordinated flows selected to meet the requirement of central user–specific QoS. In the Control Plane, we maintain an access route table to support the flow-selecting strategy. By choosing a flexible and appropriate routing strategy, we can prevent performance degradation due to the randomness and variance of mobile channels. Through this approach, relatively more stable services can be provided to users and the resource efficiency can be improved. On the aspect of routing algorithms, with reference to the wireless mesh network routing algorithms, we define a utility function–based routing selection algorithm, which achieves better performance.

Those highlighted aspects discussed in this chapter within FNA depict the way forward for the user-centric RAN of the 5G evolution. It is believed that, with the breakthroughs of the fundamental cellular network architecture, the future mobile network will surely have new performance improvements.

1.1 Related Works

Currently, mobile Internet applications and versatile mobile services are affecting every aspect of our daily life. Specifically, the dramatic increase in data traffic poses a great challenge to the network capacity and forces the mobile operators to make revolutionary changes. Besides expanding the spectrum and improving radio transmission, the mobile network architecture is considered as another potential way of further increasing the capacity of the 5G system [1,2].

Along with the evolutionary efforts for the 5G system, the cellular network topology and modeling are faced with urgent requirements for further evolution. The traditional hexagonal grid cellular network topology is believed not to be suited to centralized processing but rather to distributed deployments of RAN architecture [1], featuring as multi-tier Heterogeneous Networks (HetNet), ultra-dense small cells, and user-centric service-providing environments. The evolved network architecture should accommodate the separation of the central control entity and a large amount of distributed remote antenna elements. The BS and user association should also be evolved for on-demand service provision for users with specific QoS requirements, which are typical user-centric requirements. Moreover, an accurate depiction of the network topology modeling needs to be found for future network deployments, which will provide the operators with instructions for future network planning and optimization.

Focusing on the aforementioned requirements, there has been some research on OpenRAN, Soft Cell, and C-RAN [3-5]. The authors of [3] propose a software-defined RAN architecture, which is implemented through virtualization. For the Soft Cell concept proposed in [4], the transparent sets of BSs are provided for users. Based on the baseband pool, China Mobile Research Institute proposes C-RAN with features such as a centralized baseband unit, coordination, and cloud computing [5]. In order to solve the key challenges with regard to the way forward for C-RAN, much attention has been paid to evolved network architectures and promising key technologies [6-10]. To overcome the disadvantages of C-RANs with fronthaul constraints, heterogeneous cloud radio access networks (H-CRANs) have been proposed in [6] as a cost-effective potential solution to alleviate intertier interference and improve cooperative processing gains in HetNets in combination with cloud computing. While in [7], a fog computing-based radio access network (F-RAN) is presented, which can take full advantage of local radio signal processing, cooperative radio resource management, and the distributed storing capabilities in edge devices. These features could effectively decrease the heavy burden on fronthaul and avoid large-scale radio signal processing in the centralized baseband unit pool. In addition, some key technologies for C-RAN and H-CRAN have been proposed, including remote radio head (RRH) association strategies, inter-tier interference cancellation, and the performance optimization of a constrained fronthaul. In [8], the single nearest and N-nearest RRH association strategies are presented. Closed-form expressions for the ergodic capacity of the proposed RRH association strategies are also derived. Lately, in [9], a contract-based interference coordination framework is proposed to mitigate the inter-tier interference between RRHs and macro BSs in H-CRANs. A hybrid coordinated multipoint transmission scheme is designed for the downlink scenario of C-RAN in [10], which fulfills flexible tradeoffs between cooperation gains and fronthaul constraints.

1.2 FNA for User-Centric Radio Access Networks

Apart from the promising evolved RAN architecture mentioned in Section 1.1, the FNA was proposed lately as an evolved user-centric architecture for the radio access network of 5G, which aims to provide a set of concepts and principles to guide the development of the centralized processing network architecture and the topology for RAN evolution [11–13]. The evolved implementation scenario of FNA is shown in Figure 1.1, including the Core Network (CN), RAN deployments, and serving User Equipment (UE).

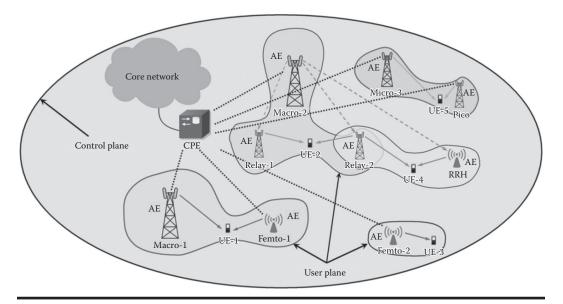


Figure 1.1 FNA with typical deployment scenarios.

The RAN of FNA consists of two main network elements. By decomposing the traditional BS into CPE and AE, FNA develops in an evolved manner. The main functions of the CPE are to maintain networking strategy, implement the signal processing, handle the CP and UP, manage all of the radio resources including the connected AEs, cope with the mobility management, and construct the on-demand user-centric service-providing environments. The CPE can be located with a macro BS or any other kinds of BSs that have the required processing ability, by which the CPE mainly functions as a logical node.

The AE is responsible for the radio signal transmission/reception. The backhaul links between the CPE and AE could be the optical fiber, wireless backhaul, wired connections, or other kinds of links. The capacity and latency features for different types of backhaul links are different, which will also be included in the consideration of resource allocations.

The AEs are selected to construct a serving set for the specific user according to its QoS requirement, which also forms the UP for the above user. The serving set may contain one or several AEs. The AE can also be a single antenna or an antenna array. According to the different transmission power limitations of their radio frequency (RF) abilities, the AEs are classified into several types that have different coverage abilities, such as the Macro AE, Micro AE, Pico AE, Femto AE, RRH AE, and so on. The AE in the serving set can also be different types, with coordination techniques supported between AEs and CPEs to provide a more flexible construction of the serving set for the specific users.

As shown in Figure 1.1, there are Macro, Pico, Femto, Relay and RRH AEs that are deployed as an underlay Scenario. UE-1 is served with a coordinated transmission mode with AEs Macro-1 and Femto-1 as the corresponding serving set according to the UE-1 QoS requirement. UE-2 is served by AEs Macro-2, Relay-1, and Relay-2. Femto-2 serves the UE-3 as the only corresponding AE. The AE Relay-2 in the serving set for UE-4 is the common node for the serving set of UE-2. For the UE-5, the AEs Micro-3 and Pico AE construct the serving set. The coordinated transmission scheme can be joint processing schemes based on the CoMP [14,15] or enhanced coordinated transmission schemes with precoding techniques applied in the transmission nodes.

The coverage area for the serving set of each UE will be amorphous because of the dynamically adaptive updated serving-set construction.

In FNA, the coordinated transmission is managed by one CPE with an arbitrary deployment of AEs within the coverage area. Similar to the phantom cells [16,17], the CP and UP are separated based on the FNA. The designated Controlling-AE implements the function of the CPE, which is handling and maintaining the Control Plane. The Data-AEs maintain their own User Plane under the control of Controlling-AEs. The Data-AEs distributed within the coverage area of a Controlling-AE are supposed to be managed by the Controlling-AE through the CPE.

According to the FNA deployments, network topology modeling will be the most fundamental research topic. For the network topology modeling, the traditional single-tier hexagonal grid network deployment model has been implemented for a long time. But with increasing deployments of HetNet and small cells, the multi-tier and ultra-dense HetNet topology cannot be depicted by the traditional hexagonal grids. The actual locations of the small cell BSs inside the future network will be more randomized, especially when the femtocells are randomly deployed in the network and the user can also have the ability to determine the ON/OFF state of their femtocells. The stochastic geometry method with the Poisson point process (PPP) model has been proposed for the aforementioned network topology [18,19], which provides good tractability for multi-tier HetNet and ultra-dense small cell deployments. The system outage capacity, mobility management, and interference management can be analyzed with closed-form solutions for many scenarios, which provide valuable theoretical instructions for the actual network planning and performance analyses.

But with more and more research focused on the PPP model, there are also some limitations found with the PPP model and the most important problem lies in the random features of the PPP. There is not a state of complete independency for the intratier and even intertier BS deployments in the actual network, which are the typical characters of field network planning and optimization. The PPP model is conservative because it deploys the BSs arbitrarily close to each other, which limits its suitability for the actual network. Recently, another model, Ginibre point process (GPP) has been proposed for depicting the multitier ultra-dense HetNet deployment topology with supporting the repulsion for deploying the BSs [20], which will be a promising tool for network topology modeling. Although the research about the GPP model is just beginning, the key challenges for RAN evolution in terms of its network topology and Stochastic Geometry approaches. Further theoretical support will also be expected to be achieved for the centralized processing but distributed deployment architecture of 5G user-centric networks.

1.3 Energy-Efficient Control Plane and User Plane Adaptation

As described in Section 1.1, CP/UP separation and adaption is one of the most significant features of FNA. In this section, we will give the CP/UP adaptation scheme for improving the system EE performance in the downlink scenario of the FNA networks. A three-step EE optimization process is designed as follows.

1.3.1 CP Construction and Adaptation with Voronoi Diagram

As depicted in Section 1.1, there is a master–slave relationship between the controlling AE and the data AE. To quantify the relationship, we focus on a simplified scenario that includes a single Controlling-AE and multiple related Data-AEs. For notational simplicity, the controlling AE is denoted as AE₀ while

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the data AEs are denoted as AE*i* (*i*=1, ..., *N*). We denote P_i as the maximum transmission power of the *i*th AE, p_c , p_0 as the allocated transmission power for the CP and UP of the controlling AE, which satisfy the constraints that $p_c \leq P_0$, $p_0 \leq P_0$. For the Data-AE, the constraints should be $p_i \leq P_i$ (*i*=1, ..., *N*), where p_i denotes the allocated transmission power of the *i*th data AE for the UP. Since the CP transmits the necessary signaling for the UP, additional coverage constraints should be made for the UP. That is, the whole coverage of all the UPs constructed by the data AEs should not surpass the coverage of the CP. Then, this constraint can be transformed as the coverage radius of data AE:

$$d_i + r_i \le r_0 \tag{1.1}$$

where:

- d_i is the distance between the controlling AE and *i*th data AE
- r_i is the coverage radius of the *i*th data AE
- r_0 is the coverage radius of the controlling AE

The coverage radius of the *i*th data AE r_i is actually determined by its transmission power p_i , while the coverage radius of the controlling AE r_0 is determined by its CP transmission power p_c . Then, Equation 1.1 can be further transformed into a power constraint of the *i*th data AE:

$$p_i \le p_c - P(d_i), i \in \{1, \dots, N\}$$
(1.2)

where $P(d_i)$ is the power attenuation from the *i*th data AE to the controlling AE. The power constraint just given still guarantees that the coverage of the UPs doesn't surpass the CP coverage, which will be used in the UP construction step of Section 1.3.2.

In order to formulate the constraints mentioned in the preceding paragraphs, a basic signal propagation model capturing pathloss as well as shadowing is defined as [21]

$$P_{rx} = K \left(\frac{r}{r_0}\right)^{-\alpha} \cdot \mathbf{\varphi} \cdot P_{tx}$$
(1.3)

where:

 P_{rx} is the receiving power

- P_{tx} is the transmission power
- *r* is the propagation distance
- α is the pathloss exponent

The random variable φ is used to model slow-fading effects and commonly follows a lognormal distribution. *K* is set to the free-space path gain at distance r_0 with the assumption of omnidirectional antennas. Here, the coverage is defined as the maximum coverage range, which satisfies the UE's minimum required received power P_{\min} . The effect of shadowing will be averaged out for the network planning of the CP's construction and adaptation. The coverage radius can be expressed as $r_i = r_0 \frac{q}{KP_i}/P_{\min}$.

In order to achieve EE optimization for CP/UP adaptation, the first step aims at constructing a seamless deployment of the CP with minimum transmission power. The Voronoi diagram, a geometric structure in computational geometry, divides the space into a number of regions consisting

of all the points closer to a specific site than to any other. As energy consumption is proportional to distance, the Voronoi diagram also defines regions where less energy consumption is required. In order to achieve better EE in the CP's construction and adaptation, we construct a Voronoi coverage area for the Controlling-AEs. The Data-AEs located within the Voronoi coverage area are controlled by the corresponding Controlling-AE.

The CP construction can be well represented by Figure 1.2, in which a Voronoi tessellation is created by the deployment of Controlling-AEs. Assuming that *C* represents the set of *n* controlling AEs in 2D Euclidean space, $d_E(c_i, x)$ denotes the Euclidean distance between the *i*th controlling AE and a position *x*. Therefore, the Voronoi coverage of the *i*th controlling AE is defined as

$$Vor(c_i) = \left\{ x \in R^2 \mid\mid \forall j \neq i, d_E(c_j, x) \right\}$$
(1.4)

In order to further adapt the transmission power of a controlling AE with an updated AE deployment or coverage area, the Voronoi coverage can be redefined based on the path loss between the controlling AE and point *x*. Let $\alpha(c_i, x)_t$ be the path loss between the *i*th controlling AE and the position *x* at time slot *t*, the Voronoi coverage will be revised as

$$Vor(c_i)_t = \left\{ x \in \mathbb{R}^2 \mid\mid \forall j \neq i, \alpha(c_i, x)_t < \alpha(c_j, x)_t \right\}$$
(1.5)

Then, the whole CP can be formed in the expression as $U_{1 \le i < n} Vor(c_i)$. This definition makes any position in the Voronoi coverage area closer to its Voronoi Controlling-AE than any others, which yields less power consumption. As a consequence, the required transmission power for the controlling AE is minimized. The simulation evaluation of the proposed CP construction and adaptation can be found in Section 1.3.4.

1.3.2 User-Centric UP Construction with Joint AE and Subchannel Allocation

The initial deployment of the UP should be constructed right after the CP construction and each user should be allocated available system resources with the user's QoS requirement. Based

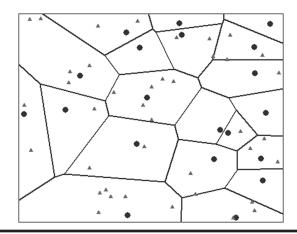


Figure 1.2 Voronoi tessellation of the CP construction. (Spots represent the locations of the controlling AEs and triangles are data AEs.)

on FNA, AE is released as a new dimensional radio resource for allocation and scheduling. By jointly allocating the AE and subchannel resources, the on-demand user-centric UP is constructed with the user's QoS requirements. The AE's transmission powers are allocated equally in this step. Moreover, the transmission power will be further adjusted based on Game theory in the third step.

1.3.2.1 Joint Resource Allocation Model for UP Construction

Considering a network with two types of Data-AEs, i.e., the Macro AE and Small cell AE, each AE has the same bandwidth and is divided into M subchannels. We set P_i as the maximum transmission power of the *i*th data AE. Meanwhile, K users are randomly distributed in the coverage area of the FNA, including K_1 users with guaranteed bit rate (GBR) service and K_2 users with non-GBR service. The space division multiple access scenario is considered, in which each subchannel of an AE can only be allocated to one user.

In order to quantify the different QoS requirements of users, the utility theory in economics is introduced to describe the characteristics of service by mapping the data rate to the user satisfaction level [22]. According to the user service QoS constraints, the utility functions of the GBR and non-GBR service are verified as the S-shaped function and convex function correspondingly [22,23]. Based on the conclusions in [24], the utility function that satisfies both types of services is obtained as Equation 1.6.

$$U(r) = \frac{E}{A + Be^{-C(r-d)}} + D$$
(1.6)

where:

r	is the data rate allocated to the user
R	is the total resource of the system
С	mainly influences the slope of the curve
A, B, D, E	mainly effect the range of the utility value
d	is the inflection point of the utility function, which indicates the user require-
	ment of the resource

By setting different parameter values, the utility function can present different characteristics, both the *S*-shaped function and the convex function. The utility functions of the GBR service $U_{real}(r)$ and non-GBR service $U_{nonreal}(r)$ are obtained from Equation 1.6 [24].

The system utility is defined as the linear weighted sum of all users' utility values. In Equation 1.7, λ represents the priority of GBR service and μ represent the priority of non-GBR service. These two weights are constrained by $\lambda, \mu \in [0,1]$ and $\lambda + \mu = 1$.

$$U_{System} = \lambda \sum_{k=1}^{K_1} U_{real}(r_k) + \mu \sum_{k=K_1+1}^{K_1+K_2} U_{non-real}(r_k)$$
(1.7)

The system utility can be further extended to include more types of service. Since the utility value represents the satisfaction level of the user, the system utility indeed represents

all users' satisfaction levels, which can provide a better reflection of system performance than throughput.

1.3.2.2 Genetic Algorithm–Based Centralized Resource Allocation

As described above, in the FNA, AE will be allocated as a new dimension of radio resource. Consequently, in the UP construction process, users with different QoS requirements are allocated with AEs and subchannels jointly. Such a multidimensional resource allocation problem can be solved by using the resource pooling–based centralized radio resources management (RRM) scheme [11]. This scheme is processed by the CPE to manage all of the available resources uniformly. Since the optimization problem of the centralized resource allocation has a large and complex search space, the genetic algorithm (GA) is implemented to obtain near-optimal solutions with a relatively fast convergence speed.

Based on the GA, a chromosome, which is a two-dimension-integer matrix, is used to represent the potential resource allocation solution. Each row of the matrix represents the resource allocation strategy for the specific user. Moreover, each row can be further divided into several parts. Each part lists the allocated elements of a particular dimension of resources. In particular, the chromosome G in the following GA process is given by

$$G = \begin{cases} a_{1,1}, a_{1,2}, \cdots, a_{1,N_a}; b_{1,1}, b_{1,2}, \cdots, b_{1,N_s}; \\ \dots \\ a_{K_1,1}, a_{K_1,2}, \cdots, a_{K_1,N_a}; b_{K_1,1}, b_{K_1,2}, \cdots, b_{K_1,N_s}; \\ a_{K_1+1,1}, a_{K_1+1,2}, \cdots, a_{K_1+1,N_a}; b_{K_1+1,1}, b_{K_1+1,2}, \cdots, b_{K_1+1,N_s}; \\ \dots \\ a_{K_1+K_2,1}, a_{K_1+K_2,2}, \cdots, a_{K_1+K_2,N_a}; b_{K_1+K_2,1}, b_{K_1+K_2,2}, \cdots, b_{K_1+K_2,N_s}; \end{cases}$$
(1.8)

where the first K_1 rows represent the resource allocation strategies of the K_1 users with GBR service, and the remaining K_2 rows represent the resource allocation strategies of the users with the non-GBR services. Each row is further divided into two parts. The first part containing N_a integers indicates the allocated AEs, while the second part containing N_s integers lists the allocated subchannels. The initial population, which includes N_p chromosomes, is generated by a random process.

In order to evaluate the chromosomes, fitness function needs to be constructed by the system utility function mentioned above. The larger the fitness value, the better the solution. Thus, the optimized objective is to maximize the fitness value, that is, to maximize the system utility. Since the utility value represents the satisfaction level of the user, the proposed algorithm tends to meet the requirements of two types of services simultaneously under the three constraints in the user-centric UP construction process. Specifically, we assume that at most N_a out of N AEs and N_s out of M subchannels can be allocated to the user k. In addition to AE and subchannel limitations, we also apply the constraint derived from Equation 1.2 in the power limitation, where we choose the minimum value between the two power constraints P_i (maximum transmission power limitation) and $p_c - P(d_i)$. By