



NAVIGATING WEATHER

A Pilot's Guide to Airborne and Datalink Weather Radar



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David Ison, Ph.D.



Navigating Weather: A Pilot's Guide to Airborne and Datalink Weather Radar by David Ison

Aviation Supplies & Academics, Inc. 7005 132nd Place SE Newcastle, Washington 98059 asa@asa2fly.com | 425-235-1500 | asa2fly.com

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About the Author

Industry expert David C. Ison has been involved in aviation for more than 35 years, during which he has flown as a flight instructor and as an ATP for both regional and major airlines flying domestic and international routes. He holds ATP Multi-Engine Land, Commercial Single-Engine Land and Sea, Gold Seal Certified Flight Instructor, Instrument Flight Instructor, Multi-Engine Flight Instructor, Ground Instructor—Instrument and Advanced, Remote Pilot, and Aircraft Dispatcher certifications.

Dr. Ison has been in aviation higher education for more than 15 years and currently holds the position of Professor, Graduate School, at Northcentral University. He graduated with a Bachelor of Science in Aviation Management from Auburn University, a Master of Science in Aeronautical Science—Operations Specialization from Embry-Riddle Aeronautical University, and a Ph.D. in Educational Studies/Higher Education Leadership with a specialization in Aviation Education from the University of Nebraska—Lincoln.

Abbreviations and Acronyms

ACARS	Aircraft Communications Addressing and Reporting	PAC	path attenuation compensation and alert
	System	PPI	plan position indicator
ACAS	airborne collision avoidance	PRF	pulse repetition frequency
	system	PWS	predictive wind shear
ADS-B	Automatic Dependent	radar	radio detection and ranging
	Surveillance-Broadcast	RAREP	radar weather report
ARS	automated radar summary	RDF	radio direction finding (RDF)
ATC	air traffic control	REACT	Rain Echo Attenuation
CRT	cathode ray tube		Compensation Technique
dBZ	decibel	RHI	range-height indicator
FIS-B	Flight Information	RRF	radar reflectivity factor
	Services-Broadcast	RWS	reactive wind shear
GCS	ground clutter suppression	SATCOM	satellite communication
GCT	ground clutter test	SELCAL	selective calling
GPWS	ground proximity warning system	STC	sensitivity time control
HEP	height evaluation position	SXM	Sirius XM
Hz	hertz	TAWS	terrain awareness and warning
IFF	identification friend or foe		system
JDOP	Joint Doppler Operations Project	TCAS	traffic collision avoidance system
LI	lifted index	TDWR	Terminal Doppler Weather Radar
LLWAS	Low-Level Wind Shear Alert	TIP	threat identification position
	System	UAT	universal access transceiver
MHz	megahertz	VIP	video integrator and processor
MND	magic number distance	VP	vertical profile
MPEL	maximum permissible exposure	VTBG	variable temperature-based gain
	level	W	watts
MUR	maximum unambiguous range	WSD	wind shear detection
NAP	normal antenna position	WSR	Weather Surveillance Radar
NEXRAD	Next Generation Weather Radar	Z _e	equivalent reflectivity
0001	out of the gate, off the ground,	ZTD	zero tilt distance
	on the ground, into the gate		
OWRC	oceanic weather reflectivity compensation		
	Compensation		

Radar History, Theory, Hardware, and Operation

HISTORY OF RADAR: FROM ANCIENT GREECE TO THE GLASS COCKPIT

Introduction

Imagine a time when hurricanes simply showed up unexpectedly. And when they did, people had little time to evacuate and minimal information about how bad things might become. Or imagine a time when heavy rains in far-off places dumped enough water to end up flooding a local river, swamping the surrounding area with little or no warning. Perhaps even more frightening is to envision yourself flying along in the clouds without any real-time weather data, unable to see outside or to avoid flinching at the frequent flashes of lightning. These scenarios used to be the daily reality across the globe. Thankfully, this is no longer the case due to a range of available technologies from computers to satellites. One of the most important discoveries that improved meteorological observation, particularly for aviation, was radio detection and ranging, known more commonly as *radar*. Radar came to be partly out of necessity and partly by accident, eventually being widely adopted by aviation for safety. Let's take a brief look into how radar was discovered and the journey it took to secure a prime place in the cockpit.

Discovering Radar

While radar itself is a recent discovery in the grand scheme of human history, essentially being a twentieth century (CE) invention, the system's principles were known as far back as the sixth century BCE. The Greeks knew of electromagnetism, the relationship between magnetic fields and electrical current, and even experimented with devices to generate static electricity. Over time, the study of electromagnetism began to become more sophisticated, yielding various benefits to science. Although there are varying claims about when the magnetic compass was invented and by whom, it is widely accepted that it came into use sometime around the thirteenth century CE, obviously revolutionizing navigation and geography.

It was not until the nineteenth century that electromagnetic concepts with which most of us today are familiar were discovered. More specific and useful details about electricity emerged at this time, such as the discovery and measurement of resistance and capacitance. By the 1830s, a metallic wire was used to transmit telegraph messages. In 1861, the United States completed a transcontinental telegraph system, followed in 1866 by the installation of a transatlantic connection.

All of this electromagnetic tinkering led German scientist Heinrich Hertz to discover how to alternate voltage to radiate electrical energy through the use of a dipole antenna. He also found that various substances could reflect this energy. By the end of the nineteenth century, inventors Nikola Tesla and Guglielmo Marconi extended Hertz's theories to develop the means of wirelessly sending telegraph messages, i.e., *radio* waves. In fact, in 1900, voice transmission via such waves was made possible due to their findings. Tesla also theorized that electrical waves could be reflected off objects, such as ships, to determine

their positions and speeds. A few years later, in 1904, Christian Hülsmeyer was awarded a patent in Britain for the use of radio waves to detect objects, demonstrating the system on riverboats along the Rhine River near Köln, Germany. This early system had a range of approximately three miles, although it could not determine the actual range of objects because its transmissions were not pulsed (though British researchers in the 1920s would later solve this issue). Oddly, Hülsmeyer's invention was all but forgotten for more than two decades while other electromagnetic advances were pursued.

The 1930s saw the increasing threat of yet another war in Europe, with aircraft rapidly becoming a strategic tool in the next conflict. In response, Germany, Russia, France, Italy, Japan, the United States, Britain, and others began to research effective means of detecting aircraft and ships in earnest. By 1933, Germany revived the efforts of Hülsmeyer leading to the ability to detect ships and aircraft at a range of seven miles, laying a foundation to pursue more sophisticated recognition systems. In 1935,



British researcher Robert Watts demonstrated aircraft detection with radio waves up to a range of eight miles, and soon after, in 1936, the U.S. National Research Laboratory was able to achieve the same feat using a pulsed wave system.

Because of its proximity to the growing German threat, England began building a series of radio direction finding (RDF) stations in 1936 along the English Channel coast, which became known as *Chain Home* (see Figure 1-1). Chain Home was considered operational by the outbreak of World War II, with its range extending beyond parts of the French coastline within the first year of the conflict. Information about detected aircraft was telephoned to a *filter room*, which passed the details on to scramble intercepts and to warn potential targets. The Germans, too, had a system ready for the outbreak of war named *Freya*, which was steerable and semi-mobile. Freya had a range of up to 100 miles and was used for early warning purposes (see Figure 1-2).

While undoubtedly helpful to both sides of the war, neither radar system was very operationally flexible. Chain Home required 360-foot-tall towers to broadcast its long-wavelength energy, and while Freya was more manageable and movable, it was far from small. It was quickly determined that smaller, more portable units would provide tactical advantages as they could be fitted on ships, submarines, aircraft, and vehicles. The missing link was a capable, small, high-powered, short-wavelength generator known as a magnetron. Although various countries had developed versions of magnetrons since the 1920s, it was not until 1940 that scientists at the University of Birmingham in England created the multi-resonant cavity magnetron (see Figure 1-3). This device allowed for the fine-tuning of wavelengths at high power, about one hundred times as strong as anything previously used, all within a



FIGURE 1-1.

Chain Home antennae in England along the English Channel coast.¹



FIGURE 1-2.

Freya—the German's portable radar system.²

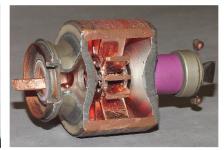


FIGURE 1-3.

Picture of a cavity magnetron such as those used in early radar systems.³

portable-sized box. Fearing the possible invasion by Germany and the prospect of falling behind Axis manufacturing capabilities, the British government sent an example of this new magnetron to the United States. Finding a home at the Radiation Laboratory at the Massachusetts Institute of Technology (MIT), the invention was refined and began to be produced in quantity.

With the U.S. industrial strength behind manufacturing, the use of radio waves for object detection immediately took off. The U.S. Navy quickly coined the term *radar* to describe the resulting radio detection and ranging system, and more than 150 models of radar were eventually produced for just about every kind of military application. Additionally, the radar *scope*, the circular display with range rings we often associate with radar, termed the plan position indicator (PPI), began to be put into use. While these radars were primitive compared to modern versions, they worked well enough to turn the tables of the air war in Europe. Radar even detected Japanese aircraft on their run to bomb Pearl Harbor, but they were erroneously dismissed as U.S. training aircraft until it was too late.

Toward the end of World War II, additional improvements to radar were made, including pulse-Doppler radar. The primary advantage of adding Doppler capabilities to radar is that it makes it easier to detect moving objects. However, other advantages of Doppler, such as detecting Doppler shift (movement away from or toward the transmitter), would have to wait for computer processing capabilities that were not yet available.

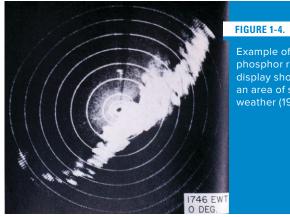
Use of Radar for the Detection of Weather

The initial purpose of radar was for tactical military use. Yet when the war came to an end, radar technology became declassified, thus opening it up to additional adaptations. The adoption of radar by meteorologists was not strictly purposeful, at least not initially. In actuality, weather was initially considered a nuisance to radar operations because it reduced the range of Chain Home. By 1941, the British military caught on to the ability of radar to detect weather. Both the British and MIT scientists began to accumulate knowledge on how weather appeared on radar, as well as the effects weather had on the system throughout the war. Radar's ability to assess and monitor weather helped the war effort, and it was adopted specifically for meteorological purposes later in the war. By 1945, radars were set up to monitor weather in East India, which paved the way for more widespread installation elsewhere. In 1946, the now declassified U.S. Navy radar units were given to the U.S. Weather Bureau. Weather research quickly ensued with projects in Florida and Ohio that explored thunderstorms in detail. These projects led to the detection of convective system updrafts and downdrafts and ways to improve radar range.

In the 1950s, the military developed weather-specific CPS-9 X-band radars for military bases. Unfortunately, data from these sets were not readily available to civilian outlets. The lack of weather information for non-military personnel was highlighted by severe, damaging storms that ripped across the United States in 1955, prompting the government to call for broad-coverage, civilian weather radars, which became known as the Weather Surveillance Radar-57 (WSR-57). This system required a radar operator to interpret difficult-to-view data displayed on a monochrome phosphor screen, which was then coded on teletype as a

radar report, or RAREP, every hour (see Figure 1-4). By 1961, such reports were sent via facsimile and quickly became a vital enhancement to aviation safety.

The 1960s brought forth crucial improvements to weather radar features, thanks to the discovery of the "Z-R" relationship. Researchers discovered that there is a correlation between reflectivity of radar energy and the rate (i.e., intensity) of rainfall. Simply, the greater the amount



Example of early display showing an area of severe weather (1944).4

of a radar signal that is reflected, the harder the rainfall. By 1968, a video integrator and processor (VIP) was added to contour radar images, making weather intensity much easier to discern. The VIP quantified radar returns (i.e., echoes) into groups based on intensity. There were six VIP levels of intensity available corresponding to rainfall rate estimates. Initially, the contouring was in the form of shades of white, grey, and black. The addition of the VIP system paved the way for future computer analysis and processing.

By the 1970s, computers were aiding more in image processing, making the appearances of weather easier for users to identify. Cathode ray tube (CRT) displays became more commonplace, as did color imagery and contouring. The digital VIP was introduced, which averages returns in a location for a period before displaying them to ensure images do not randomly change. During this time, radar operators still had to code echoes manually and then computers generated a graphic depiction. This soon became displaced by automated radar summary charts (ARS) in which computers converted VIP levels into images. As can be imagined, this greatly improved the information available to all weather stakeholders, including pilots. In 1974, WSR-74 was added to fill in the gaps that existed in WSR-57 coverage, significantly increasing the utility of the overall system.

The mid-1970s saw several accidents caused by weather phenomena that highlighted weaknesses in the general understanding of thunderstorms and the ability to detect storm hazards. The first was Pan Am Flight 806 in 1974. The Boeing 707 crashed on approach to Pago Pago, American Samoa, killing 97 occupants. The cause was determined to be tardy identification and response to wind shear. The following year, Eastern Air Lines Flight 66, a Boeing 727, crashed on approach to New York's John F. Kennedy International Airport due to wind shear, killing 113 people. These crashes, along with the rapid increase in jet aircraft traffic, prompted researchers to figure out more about thunderstorms and wind shear and, most importantly, how they potentially impact aircraft operations.

In 1976, a researcher named T. Theodore Fujita characterized microbursts—strong, smallscale wind shear events—and their danger to aviation. This research increased understanding of storm dynamics, detection, and meteorology. Additionally, these discoveries helped the Next Generation Weather Radar (NEXRAD) systems to be developed, thanks in part to the U.S. Air Force and the National Weather Service working together in a program known as the Joint Doppler Operations Project (JDOP). Research into gust fronts, sea breeze fronts, and other forms of wind shear, in addition to the Eastern Flight 66 crash, eventually led to the development of the Low-Level Wind Shear Alert System (LLWAS) that ultimately would be installed at major airports across the United States. This system compares winds across the airport environment and alerts users to wind shear events occurring on or near the airfield.

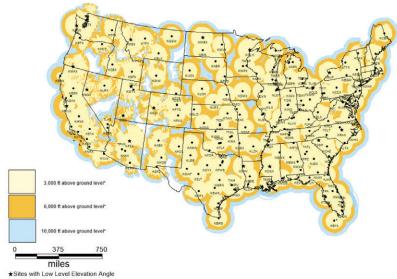
The work of the JDOP led to the push for replacing older WSR systems with NEXRAD in the form of the WSR-88D. As can be surmised from the designation, this system was put into place in 1988 and included Doppler capabilities. Thus, the radar could identify storms but also dissect the guts of the cells plus their internal movement and winds. These efforts laid the foundation for national radar coverage in the United States (see Figure 1-5) and dramatically improved the quality and quantity of weather information available to the general public.

Additional improvements have been made over time, with another significant step occurring in 2013 in which WSR was upgraded to have dual polarization. This new polarimetric radar uses radar waves polarized in two perpendicular planes to detect particle composition and distribution within storms.

FIGURE 1-5.

Map of weather radar coverage in the United States. (Note the areas blocked by terrain, especially in the Mountain West portions of the country.)7

NEXRAD - TDWR COVERAGE BELOW 10,000 FEET AGL



*Bottom of beam height (assuming Standard Atmospheric Refraction) Terrain Blockage Indicated where 50% or more of beam blocked



The future of weather radar is likely to come in the form of advanced phased array radar. These systems do not always employ a movable antenna. Instead, they use wave interference to steer radar energy. These potential improvements are a result of the military's many years using phased array radar. Phased array systems are faster and less susceptible to mechanical breakdowns. Plans exist to add phased array systems to cellular phone towers to improve coverage in locations with significant gaps.

Weather Radar Goes Airborne

As previously mentioned, radar was initially used onboard aircraft for tactical purposes, with the weather being more of a nuisance rather than the desired target. This began to change as the utility of weather detection became more apparent during and after World War II. The primary weather concern for aviation was severe weather, namely thunderstorms, which along with their associated turbulence, hail, lightning, and heavy precipitation were one of the leading causes of crashes at the time. In 1945, U.S. airlines began to explore the use of airborne weather radar. Between 1945 and 1946, Trans World Airlines (TWA) worked with Bell Labs and West Electric to assess primitive weather radar on board a C-47 (DC-3) aircraft. From 1947 to 1949, American Airlines also flew radar-equipped C-47 aircraft with AN/APS-10 radar to detect and study thunderstorms in the Denver area. Further research conducted by United Airlines led to the idea that radar was critical to aviation safety.

The first commercial aircraft with airborne weather radar was a DC-6 that took flight in 1950. United Airlines named their radar systems "Sir Echo," complete with its own logo. The availability of airborne weather radar was quickly adopted as a marketing tool, assuring passengers of improved rides and increased safety. Following a series of crashes suspected to be associated with convective weather as well as the technological strides being made in radar systems, the FAA began to require weather radar for all air carrier aircraft, a precedent that remains to this day. A 1955 study by United Airlines found immediate dividends to the radar requirement. The company reported a sharp decline in static discharge events and a decrease in turbulence incidents as well as less time spent in bumpy conditions. Further, there were 80 percent fewer weather incidents reported by flight crews as well as a reduction in delays and detours.

Although airborne weather radar use became widespread, there were still deficiencies in technology and knowledge of severe weather dynamics. Most systems in use were X-band radars, which were susceptible to attenuation, a phenomenon where precipitation absorbs, scatters, or blocks radar energy, distorting the intensity level displayed to pilots. This weakness was brought to the spotlight by the 1977 crash of Southern Airways Flight 242 in which the pilots misinterpreted the presence of attenuation on their radar display, essentially flying into an area of extreme weather. This crash was instrumental in highlighting the need for better weather information provided by air traffic control, improved pilot training, and technological improvements. Soon after that, manufacturers developed and adopted attenuation compensation algorithms for radar units. Additionally, some models included indications to pilots if attenuation was suspected, assisting them in avoiding areas of severe weather.

8 NAVIGATING WEATHER

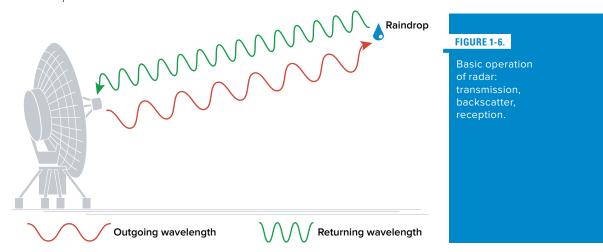
Since the early 1980s, airborne weather radar has been incrementally improved in a variety of ways. One of the first improvements was migration from monochrome to color displays. Doppler technology was also added to airborne systems to provide better attenuation prevention and specific detection of turbulence and wind shear. More recent enhancements include automated operations such as *auto scan* and *auto tilt*. Radars have become comprised of solid-state components and have reaped the rewards of increased computing speeds and capacities. Vertical profile radar now provides three-dimensional imagery of storms, further enhancing weather awareness. Also, radar information is no longer isolated to a stand-alone radar display; instead, it is often integrated with glass cockpit avionics allowing the weather to be overlaid on navigation data, including routes, airports, procedures, and navigational aids. Computers can now analyze how fine particles are moving in a column of air to predict possible wind shear, notifying pilots visually and aurally. The amount of weather situational awareness that these improvements have brought forth in relation to earlier systems has tremendously increased aviation safety.

Summary

Since World War II, radar has become a more integral part of aviation and a critical contributor to its safety. Ground-based radar now provides significant coverage across the United States and other parts of the world to better inform meteorologists and aviation stakeholders of the location, movement, and characteristics of severe weather threats. Airborne weather radar technology has matured into sophisticated systems embedded in avionics suites, providing pilots the ability to examine and dissect proximate weather to circumnavigate hazards and maximize aircraft occupants' comfort. The availability of weather radar on modern airliners has all but eliminated the run-ins with severe weather, especially microbursts, which were much more common before radar's adoption. As technology continues to improve and prices thereof decrease, it can be anticipated that radar data will become better and more available to a broader spectrum of users. It is evident that radar has been a game changer for aviation operations and system safety.

RADAR THEORY BASICS

The premise behind radar theory is relatively simple: electromagnetic energy is emanated from a source and travels outwards, and some of this energy bounces off objects within its path and returns to the source, which has the capacity to receive it (see Figure 1-6). Some overly simplified analogies are also used to describe how radar does its work, such as bats' echolocation to find their prey or submarines' use of sonar to help pinpoint theirs. If these explanations suffice to satisfy your curiosity on the details about how electromagnetic energy is used to detect weather, then skip to the next section on hardware. Otherwise, let's dig a little deeper.



Characteristics of Electromagnetic Waves

Wavelength

Electricity and magnetic fields go hand in hand: when you have one, you always have the other. Electric motors operate on this principle as they pass electricity through coils that impart magnetic fields onto internal magnetic components, which operate the motor. An aircraft alternator uses the same principle in reverse—the engine provides the movement, which turns gears connected to the magnets in the alternator, which then impart magnetic fields on adjacent coils, creating the flow of electrons, i.e., electricity. Electromagnetic fields tend to oscillate, resulting in waves of energy that radiate outwards (thus the term *radiation*). These waves move at approximately the speed of light, or 300 million meters per second.

Waves are described in various ways, and each of these characteristics can affect the utility (and possibly the danger) of such waves (see Figure 1-7). For radar, the most critical attribute of energy waves is the wavelength—the measurement of a full cycle of a wave, i.e., the measurement from one wave peak to the next (see Figure 1-8). Atmospheric particles react disparately to different wavelengths. For example, visible light has a very short wavelength on the electromagnetic spectrum and is easily attenuated (a fancy term we use for "being blocked or absorbed") by particles. This is why clouds that produce precipitation appear dark. Thus, it is evident that radar energy needs to penetrate clouds to evaluate precipitation while not passing through without bouncing some of the energy back to the radar antenna.

Wavelengths dictate the design of the transmitter, receiver, and antenna. The selection of a suitable radar wavelength is a compromise among transmitter size, cost, and detection needs. Shorter-wave systems are smaller and less expensive and are therefore ideal for airborne applications; however, shorter waves are more susceptible to attenuation. Because size (as well as cost) is less of an issue for radar systems used by the National Weather Service (NWS), longer wavelengths are used, which allow for a more robust analysis of weather phenomena.

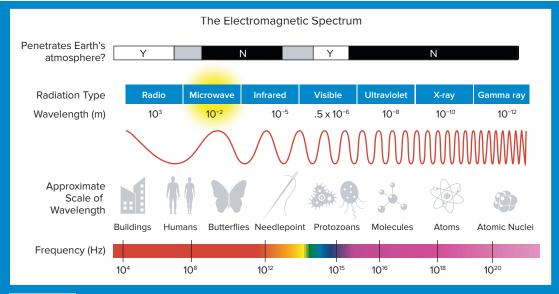


FIGURE 1-7.

Electromagnetic energy wavelengths with examples of sizes of waves.¹⁰ (Note: radar operates in the microwave range.)

The most common type of radar used onboard aircraft falls within the X-band (3 cm wavelength). Ground-based radars are either C-band (5 cm wavelength), commonly used outside the United States, or S-band (10 cm wavelength), which is used on U.S. WSR units.

Frequency

Another measure used to describe waves is frequency, which is the number of wavelengths that pass a point within each second (see Figure 1-8). It is measured in hertz (Hz), which represents the number of cycles per second. Frequency is more of an engineering concern than an operational one, but, as one can imagine, there is an inverse relationship between wavelength and frequency: waves move at a constant speed, so with smaller (narrower) waves, a higher frequency of wavelengths will fit into a second's worth of distance traveled. Most airborne weather radars on civilian aircraft operate within the frequency range of 8,000 to 12,500 megahertz (MHz).



WHERE DID THOSE BANDS GET THEIR NAMES?

If you are ever wondering how the different radar frequency bands got their names, you came to the right place. The "X" descriptor came from the World War II era in which this frequency range was still a secret (think X-Files). "S" band stands for short wavelength, while "C" is for compromise between short and longer wavelengths.

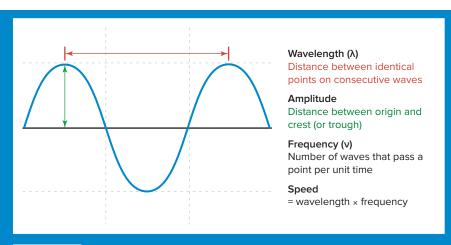
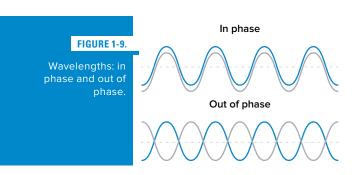


FIGURE 1-8.

Terms used to describe radio waves.

Amplitude and Phase

The term *amplitude* refers to the height of a radio wave from its origin to its crest or peak (measured either up [positive] or down [negative]) (see Figure 1-8). Amplitude is described as a measure of wave power and is indicated in watts (W). For meteorological purposes, power is vital in terms of the amount of radar energy transmitted versus the amount received back at the antenna—i.e., the amount of energy reflected. Phase refers to the synchronization of two or more



frequencies and is something quite crucial to Doppler radar systems. A wave is considered to be *in phase* when the two or more wavelengths line up on top of one another, thus resonating at the same frequency. When one or more waves are *out of phase*, they are not aligned and occur at different frequencies (see Figure 1-9).

Polarization

Basic radar systems transmit a signal with a fixed orientation or polarization of the radio wave crest. Usually this is aligned with the horizontal axis. On polarimetric radar systems, which are becoming more common, signals are polarized in both the horizontal and vertical axes. This allows for radars to provide insights into the size and structure of particles that reflect the radar energy. Polarimetric radar provides a view of a larger slice of the sky, allowing for more in-depth analysis and interpretation, such as estimating droplet sizes, distinguishing between rain and snow, and approximating rainfall rate (see Figure 1-10).

