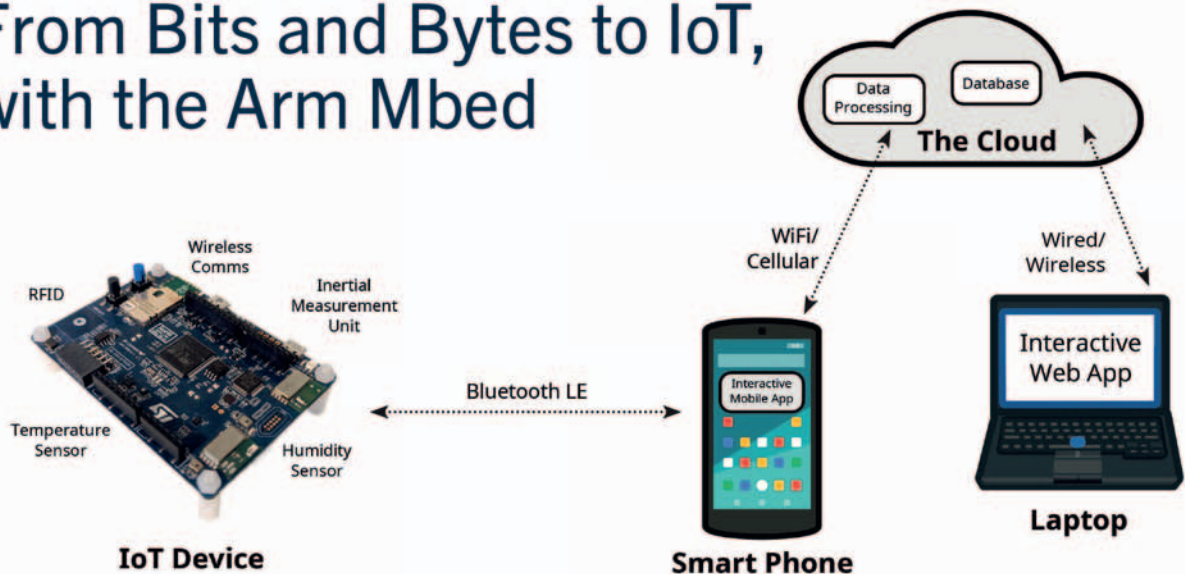


# FAST AND EFFECTIVE EMBEDDED SYSTEMS DESIGN

From Bits and Bytes to IoT,  
with the Arm Mbed



Tim Wilmshurst, Rob Toulson and Tom Spink

# ***Fast and Effective Embedded Systems Design***

This page intentionally left blank

# ***Fast and Effective Embedded Systems Design***

*From Bits and Bytes to IoT,  
with the Arm Mbed*

**Third Edition**

Rob Toulson  
Tim Wilmshurst  
Tom Spink

Amsterdam • Boston • Heidelberg • London • New York • Oxford • Paris  
San Diego • San Francisco • Singapore • Sydney • Tokyo  
Newnes is an imprint of Elsevier



**Newnes**  
An imprint of Elsevier

Academic Press is an imprint of Elsevier  
125 London Wall, London EC2Y 5AS, United Kingdom  
525 B Street, Suite 1650, San Diego, CA 92101, United States  
50 Hampshire Street, 5th Floor, Cambridge, MA 02139, United States  
The Boulevard, Langford Lane, Kidlington, Oxford OX5 1GB, United Kingdom

Copyright © 2025 Elsevier Ltd. All rights are reserved, including those for text and data mining, AI training, and similar technologies.

Publisher's note: Elsevier takes a neutral position with respect to territorial disputes or jurisdictional claims in its published content, including in maps and institutional affiliations.

No part of this publication may be reproduced or transmitted in any form or by any means, electronic or mechanical, including photocopying, recording, or any information storage and retrieval system, without permission in writing from the publisher. Details on how to seek permission, further information about the Publisher's permissions policies and our arrangements with organizations such as the Copyright Clearance Center and the Copyright Licensing Agency, can be found at our website: [www.elsevier.com/permissions](http://www.elsevier.com/permissions).

This book and the individual contributions contained in it are protected under copyright by the Publisher (other than as may be noted herein).

#### Notices

Knowledge and best practice in this field are constantly changing. As new research and experience broaden our understanding, changes in research methods, professional practices, or medical treatment may become necessary.

Practitioners and researchers must always rely on their own experience and knowledge in evaluating and using any information, methods, compounds, or experiments described herein. In using such information or methods they should be mindful of their own safety and the safety of others, including parties for whom they have a professional responsibility.

To the fullest extent of the law, neither the Publisher nor the authors, contributors, or editors, assume any liability for any injury and/or damage to persons or property as a matter of products liability, negligence or otherwise, or from any use or operation of any methods, products, instructions, or ideas contained in the material herein.

ISBN: 978-0-323-95197-5

For information on all Elsevier publications visit our website at  
<https://www.elsevier.com/books-and-journals>

*Publisher:* Katey Birtcher  
*Acquisition Editor:* Stephen R. Merken  
*Editorial Project Manager:* Sara Valentino  
*Production Project Manager:* Nandhini Thanga Alagu  
*Cover Designer:* Mark Rogers

Typeset by TNQ Technologies



# Contents

<i>Introduction .....</i>	<i>xv</i>
<i>Acknowledgments .....</i>	<i>xix</i>

## ***PART 1: Essentials of Embedded Systems, and Developing with Mbed .. 1***

<b><i>Chapter 1: Embedded Systems, Microcontrollers, and Arm .....</i></b>	<b><i>3</i></b>
1.1 Introducing Embedded Systems .....	3
1.1.1 What is an Embedded System?.....	3
1.1.2 Fast Forward to the Internet of Things .....	5
1.1.3 The Electric Car—An Abundance of Embedded Systems.....	5
1.2 Microprocessors and Microcontrollers .....	8
1.2.1 Some Computer Essentials .....	8
1.2.2 The Microcontroller .....	10
1.3 Code Development in Embedded Systems .....	11
1.3.1 Machine Code, Assembler, and High-level languages .....	11
1.3.2 Flow Diagrams and Simple Sequential Programming.....	13
1.3.3 The Development Cycle .....	14
1.4 The World of Arm .....	16
1.4.1 A Little History .....	16
1.4.2 Some Technical Detail—What Does This Word RISC Mean?.....	17
1.4.3 The Cortex Core .....	19
Chapter Review .....	22
Quiz.....	22
References.....	23
<b><i>Chapter 2: Introducing the World of Mbed .....</i></b>	<b><i>25</i></b>
2.1 Introducing the Mbed Environment .....	25
2.1.1 Mbed, Mbed Enabled, and the Mbed “Ecosystem” .....	25
2.1.2 Choosing Our Target Systems .....	26
2.2 Where Mbed Began—The Mbed LPC1768.....	27
2.2.1 Introducing the Mbed LPC1768.....	27
2.2.2 The Mbed LPC1768 Architecture .....	28
2.2.3 The LPC1768 Microcontroller .....	30
2.3 Nucleo and the F401RE Development Board .....	31

2.4 The STM32 Discovery Kit IoT Node .....	34
2.5 The Framework for Mbed Code Development.....	36
2.5.1 Using C/C++.....	36
2.5.2 The Mbed API .....	36
2.5.3 The Mbed Operating System.....	37
2.5.4 The “Bare Metal” Profile.....	39
2.6 The Studio Development Environments, and a First Program .....	39
2.6.1 Using Mbed Studio/Keil Studio Cloud .....	40
2.6.2 Adding Software Libraries .....	44
2.7 The Mbed Application Board.....	44
Chapter Review .....	48
Quiz.....	49
References.....	49
<b>Chapter 3: Digital Input and Output.....</b>	<b>51</b>
3.1 Starting to Program.....	51
3.1.1 Thinking About the First Program .....	51
3.1.2 A First Word on Timing.....	53
3.1.3 Using the Mbed API.....	55
3.1.4 Exploring the <i>while</i> Loop.....	56
3.1.5 Using Development Board External Pins .....	58
3.2 Voltages as Logic Values.....	59
3.3 Digital Output .....	61
3.3.1 Using LEDs.....	61
3.3.2 Using a Breadboard to Connect External Components.....	62
3.4 Using Digital Inputs.....	64
3.4.1 Connecting Switches to a Digital System.....	64
3.4.2 The DigitalIn API.....	65
3.4.3 Using <i>if</i> to Respond to a Switch Input .....	65
3.5 Digital Input and Output with the Application Board .....	67
3.6 Interfacing Simple Opto Devices .....	71
3.6.1 Opto-reflective and Transmissive Sensors.....	71
3.6.2 Connecting an Opto-sensor to an Mbed Development Board .....	72
3.6.3 Seven-Segment Displays.....	73
3.6.4 Connecting a Seven-Segment Display to the Mbed Target .....	75
3.7 Switching Larger DC Loads.....	77
3.7.1 Applying Transistor Switching.....	77
3.7.2 Switching a Motor with the Mbed.....	79
3.7.3 Switching Multiple Seven-segment Displays.....	81
3.8 Mini-project: Letter Counter .....	82
Chapter Review .....	82
Quiz.....	82
References.....	85

<b>Chapter 4: Analog Output and Pulse Width Modulation .....</b>	<b>87</b>
4.1 Introducing Data Conversion.....	87
4.1.1 The Digital-to-Analog Converter .....	87
4.2 Analog Outputs on the Mbed LPC1768 .....	89
4.2.1 Constant Output Voltages .....	90
4.2.2 Sawtooth Waveforms .....	90
4.2.3 Testing the DAC Resolution.....	93
4.2.4 Generating a Sine Wave .....	93
4.3 Another Way of Replicating Analog Output: Pulse Width Modulation.....	94
4.4 Pulse Width Modulation in the Mbed Environment.....	97
4.4.1 Using the Mbed PWM Sources.....	97
4.4.2 Some Trial PWM Outputs .....	97
4.4.3 Speed Control of a Small Motor.....	99
4.4.4 Generating PWM in Software .....	100
4.4.5 Servo Control .....	102
4.4.6 Producing Audio Output.....	104
Chapter Review .....	106
Quiz.....	107
<b>Chapter 5: Analog Input .....</b>	<b>109</b>
5.1 Analog-to-Digital Conversion.....	109
5.1.1 The Analog-to-Digital Converter .....	109
5.1.2 Range, Resolution, and Quantization.....	110
5.1.3 Sampling Frequency .....	113
5.1.4 Analog Input with the Mbed .....	114
5.2 Combining Analog Input and Output.....	114
5.2.1 Controlling LED Brightness by Variable Voltage .....	114
5.2.2 Controlling LED Brightness by PWM.....	117
5.2.3 Controlling PWM Frequency .....	117
5.3 Processing Data from Analog Inputs .....	119
5.3.1 Displaying Data on the Computer Screen—printf( ) and the Serial Terminal ..	119
5.3.2 Scaling ADC Outputs to Recognized Units.....	122
5.3.3 Applying Averaging to Reduce Noise.....	122
5.4 Some Simple Analog Sensors .....	123
5.4.1 The Light-Dependent Resistor.....	123
5.4.2 Integrated Circuit Temperature Sensors.....	125
5.5 Exploring Data Conversion Timing .....	126
5.5.1 Estimating Conversion Time and Applying Nyquist.....	126
5.6 Introducing the Debugger .....	128
5.6.1 A Motor Control Program .....	128
5.6.2 Simple Use of the Debugger .....	131
5.7 Mini-Projects .....	133
5.7.1 Two-Dimensional Light Tracking .....	133
5.7.2 Temperature Alarm .....	134



Chapter Review .....	134
Quiz.....	135
References.....	135

**Chapter 6: Interrupts and Timers..... 137**

6.1 Thinking about Time .....	137
6.2 Responding to External Events .....	138
6.2.1 Polling .....	138
6.2.2 Introducing Interrupts .....	139
6.3 Interrupts with the Mbed Operating System.....	140
6.4 Getting Deeper into Interrupts.....	143
6.4.1 Interrupts on the LPC1768 .....	145
6.4.2 Testing Interrupt Latency.....	145
6.4.3 Disabling Interrupts.....	147
6.4.4 Interrupts from Analog Inputs.....	147
6.4.5 Conclusion on Interrupts.....	149
6.5 An Introduction to Timers .....	149
6.5.1 The Digital Counter .....	149
6.5.2 Using the Counter as a Timer .....	150
6.5.3 Timers in the Mbed Environment .....	150
6.6 Using the Mbed Timer.....	151
6.6.1 The Timer API .....	151
6.6.2 Using Multiple Mbed Timers .....	152
6.7 Using the Mbed Timeout.....	154
6.7.1 A Simple Timeout Application .....	154
6.7.2 Further Use of Timeout .....	156
6.7.3 Timeout Used to Test Reaction Time .....	157
6.8 Using the Mbed Ticker.....	159
6.8.1 Using Ticker for a Metronome.....	160
6.8.2 Reflecting on Multi-tasking in the Metronome Program .....	163
6.9 The RTC.....	163
6.10 Switch Debouncing.....	165
Chapter Review .....	167
Quiz.....	168

**Chapter 7: Starting with Serial Communication ..... 169**

7.0 A Word on Inclusive Language.....	169
7.1 Introducing Synchronous Serial Communication .....	169
7.2 Serial Peripheral Interface .....	171
7.2.1 Introducing SPI .....	171
7.2.2 SPI in the Mbed Environment.....	173
7.2.3 Setting up an Mbed SPI Master .....	174
7.2.4 Creating an SPI Data Link .....	176
7.3 Intelligent Instrumentation and an SPI Accelerometer .....	180
7.3.1 Introducing the ADXL345 Accelerometer.....	181

7.3.2 Developing a Simple ADXL345 Program .....	182
7.4 Evaluating SPI.....	184
7.5 The Inter-integrated Circuit (I <sup>2</sup> C) Bus .....	185
7.5.1 Introducing the I <sup>2</sup> C Bus.....	185
7.5.2 I <sup>2</sup> C with the Mbed OS.....	187
7.5.3 Setting Up an I <sup>2</sup> C Data Link.....	187
7.6 Communicating with I <sup>2</sup> C-Enabled Sensors.....	192
7.6.1 The TMP102 Sensor .....	192
7.6.2 The SRF08 Ultrasonic Range Finder.....	195
7.7 Evaluating I <sup>2</sup> C.....	197
7.8 Asynchronous Serial Data Communication .....	198
7.8.1 Introducing Asynchronous Serial Data .....	198
7.8.2 Applying Asynchronous Communication in the Mbed Environment.....	199
7.8.3 Applying Asynchronous Communication with the Host Computer .....	202
7.9 USB .....	203
7.9.1 Introducing USB .....	204
7.9.2 USB Capability in the Mbed Environment.....	205
7.9.3 Using the Mbed to Emulate a USB Mouse .....	205
7.9.4 USB On-the-Go.....	207
7.10 Using Serial on the ST IoT Discovery Board .....	207
7.11 Mini-projects .....	210
7.11.1 Multi-node I <sup>2</sup> C Bus.....	210
7.11.2 Vibrating Beam Acceleration Threshold Detection.....	210
Chapter Review .....	211
Quiz.....	212
References.....	213
<b>Chapter 8: Liquid Crystal Displays.....</b>	<b>215</b>
8.1 Display Technologies.....	215
8.1.1 Introducing Liquid Crystal Technology .....	215
8.1.2 Liquid Crystal Character Displays .....	216
8.2 Using the PC1602F LCD.....	218
8.2.1 Introducing and Connecting the PC1602F Display .....	218
8.2.2 Using Modular Coding to Control the LCD.....	220
8.2.3 Initializing the Display .....	220
8.2.4 Sending Display Data to the LCD .....	222
8.2.5 Calling the LCD Functions from main( ).....	224
8.2.6 Adding Data to a Specified Location.....	225
8.3 Using the Mbed TextLCD Library.....	226
8.4 Displaying Analog Input Data on the LCD.....	228
8.5 Pixel Graphics—Implementing the NHD-C12832 Display.....	230
8.6 Color LCDs and the uLCD-144-G2.....	237

8.7 Mini-projects .....	241
8.7.1 Digital Spirit Level .....	241
8.7.2 A Self-contained Metronome .....	241
Chapter Review .....	242
Quiz .....	242
References.....	243
<b>Chapter 9: Programming in Real Time.....</b>	<b>245</b>
9.1 Multitasking and Real Time .....	245
9.2 Scheduling.....	247
9.2.1 Scheduling and Context Switching .....	247
9.2.2 Thread States.....	250
9.3 The Mbed RTOS.....	252
9.4 Writing Multi-threaded Programs .....	254
9.4.1 Defining and Writing Threads.....	254
9.4.2 Two-threaded Programs .....	255
9.4.3 A Multi-threaded Program.....	256
9.4.4 Setting Thread Priority .....	259
9.5 The Mutex .....	261
9.5.1 The Mutex Concept .....	261
9.5.2 A Mutex Program .....	263
9.6 The Semaphore .....	265
9.6.1 The Semaphore Concept.....	265
9.6.2 Programming with Semaphores.....	267
9.7 Using Interrupts with the RTOS.....	270
9.8 Queues and Memory Pools.....	272
9.8.1 The Queue Concept .....	272
9.8.2 Programming with Queues and Memory Pools.....	272
9.9 The “Bare Metal” Profile.....	276
Chapter Review .....	276
Quiz .....	277
References.....	280
<b>Chapter 10: Memory and Data Management .....</b>	<b>281</b>
10.1 A Memory Review.....	281
10.1.1 An Overview of Memory Technologies.....	281
10.1.2 Memory Mapping .....	285
10.2 Some Programming Techniques for Data and File Management .....	286
10.2.1 Using Addresses and Pointers .....	286
10.2.2 File Management in C/C++ .....	289
10.2.3 Using Data Files with the Mbed OS.....	289
10.3 The Mbed LPC1768 Local File System .....	291
10.3.1 Opening and Closing Files .....	291
10.3.2 Recovering a “Lost” Mbed LPC1768 .....	292

10.3.3 Simple File Data Transfers.....	292
10.3.4 String File Access.....	294
10.3.5 Using Formatted Data.....	295
10.4 Using External SD Card Memory.....	297
10.4.1 Simple SD Card Block Transfers.....	297
10.4.2 Creating Files with the FAT File System.....	301
10.5 Mini Project: Accelerometer Data Logging on Exceeding Threshold .....	304
Chapter Review .....	305
Quiz.....	305
References.....	306
<b>PART 2: Wireless and the Internet of Things.....</b>	<b>307</b>
<b>Chapter 11: Wireless Communication.....</b>	<b>309</b>
11.1 Introducing Wireless Data Communication.....	309
11.1.1 Some Wireless Preliminaries.....	309
11.1.2 Wireless Networks .....	312
11.1.3 A Word on Protocols.....	313
11.2 Bluetooth Low Energy.....	314
11.2.1 Classic Bluetooth .....	315
11.2.2 Bluetooth Low Energy.....	315
11.2.3 Establishing a Connection .....	316
11.2.4 Exchanging Data.....	319
11.2.5 BLE on the ST IoT Discovery Board.....	319
11.2.6 Simple BLE: Sending Data to a Smart Phone .....	320
11.2.7 Evaluating BLE.....	326
11.3 Zigbee.....	328
11.3.1 Introducing Zigbee.....	328
11.3.2 Introducing XBee Wireless Modules .....	330
11.3.3 Introducing the XCTU Software .....	331
11.3.4 Configuring an XBee Pair .....	333
11.3.5 Implementing Zigbee Links.....	334
11.3.6 Introducing the XBee API.....	338
11.3.7 Applying the XBee API .....	339
11.3.8 Conclusion on Zigbee and Further Work.....	343
11.4 LoRa and LoRaWAN.....	343
11.5 Mini Projects.....	345
11.5.1 BLE Mini Project.....	345
11.5.2 Zigbee Mini Project.....	345
Chapter Review .....	346
Quiz.....	346
References.....	347

<b>Chapter 12: Towards the Internet of Things.....</b>	<b>349</b>
12.1 What is the Internet of Things? .....	349
12.1.1 An IoT Overview .....	349
12.1.2 Applications of the IoT.....	351
12.1.3 A Little IoT History.....	352
12.2 Core Components in the IoT.....	353
12.2.1 Sensors and Actuators.....	353
12.2.2 Connectivity .....	354
12.2.3 Processing: Edge Computing.....	356
12.2.4 Processing: Cloud Computing .....	357
12.2.5 Mobile and Web Applications.....	359
12.3 Case Studies .....	359
12.3.1 A Smart Lightbulb .....	359
12.3.2 A Wearable Fitness Tracker.....	361
12.4 Building a Full-stack IoT System: An Activity Tracker.....	362
12.4.1 Overview .....	363
12.4.2 Getting Started with Google Cloud.....	364
12.4.3 Firestore.....	365
12.4.4 Cloud Functions .....	367
12.4.5 Preparing the Embedded Device .....	373
12.4.6 Sending Movement Data .....	376
12.4.7 Building the Mobile App: Designing the User Interface .....	377
12.4.8 Building the Mobile App: Reading and Processing Activity Data.....	381
12.5 Summary .....	389
12.6 Mini Projects.....	390
12.6.1 Smart Lightbulb Simulation .....	390
12.6.2 Reconfiguring the Activity Tracker Example .....	390
Chapter Review .....	390
Quiz.....	391
References.....	393
<b>Chapter 13: Further Aspects of the IoT.....</b>	<b>395</b>
13.1 Ethernet .....	395
13.2 Wi-Fi.....	399
13.3 Getting Data from A to B .....	402
13.3.1 Routing and IP Addresses.....	403
13.3.2 The Role of the Gateway .....	405
13.4 Data Exchange .....	407
13.4.1 TCP and UDP .....	407
13.4.2 HTTP and HTTPS .....	408
13.4.3 Data Interchange Formats.....	410
13.5 Challenges and Risks in Building IoT Systems .....	412
13.5.1 Security and Privacy .....	413
13.5.2 Dealing with IoT Scale and Complexity .....	415

13.6 Powering the IoT “Things” .....	416
Chapter Review .....	418
Quiz.....	419
References.....	420
<b>PART 3: Deeper Details .....</b>	<b>421</b>
<b>Chapter 14: Working Directly with the Control Registers.....</b>	<b>423</b>
14.1 Introduction: Given the Mbed OS, Why Learn about Control Registers? .....	423
14.2 Control Register Concepts.....	424
14.3 Digital I/O .....	426
14.3.1 LPC1768 Digital I/O Control Registers.....	426
14.3.2 A Digital Output Application.....	427
14.3.3 Adding Further Digital Outputs .....	429
14.3.4 Digital Inputs.....	431
14.4 Getting Deeper into the Control Registers .....	433
14.4.1 Pin Select and Pin Mode Registers.....	433
14.4.2 Power Control and Clock Select Registers.....	435
14.5 Using the DAC.....	437
14.5.1 LPC1768 DAC Control Registers .....	438
14.5.2 A DAC Application .....	438
14.6 Using the ADC .....	440
14.6.1 LPC1768 ADC Control Registers .....	440
14.6.2 An ADC Application .....	442
14.6.3 Changing ADC Conversion Speed.....	445
14.7 A Conclusion on Using the Control Registers.....	447
Chapter Review .....	447
Quiz.....	448
<b>Chapter 15: Some Hardware Insights: Clocks, Resets, and Power Supply.....</b>	<b>449</b>
15.1 Hardware Essentials—Power Supply .....	449
15.1.1 Powering the LPC1768 Microcontroller .....	449
15.1.2 Powering the Mbed LPC1768 .....	451
15.2 Clock Sources and Their Selection .....	453
15.2.1 Some Clock Oscillator Preliminaries.....	453
15.2.2 LPC1768 Clock Oscillators and the Mbed Implementation .....	454
15.2.3 Setting the LPC1768 Clock Configuration Register.....	456
15.2.4 Adjusting the LPC1768 PLL.....	458
15.2.5 Selecting the LPC1768 Clock Source.....	461
15.3 Reset .....	462
15.3.1 Power-On Reset .....	463
15.3.2 Other Sources of Reset.....	464
15.3.3 Reason for Reset.....	466
15.4 Toward Low Power.....	468

15.4.1 How Power Is Consumed in a Digital Circuit.....	468
15.4.2 A Word on Cells and Batteries.....	470
15.4.3 Microcontroller Low-Power Modes and OS Support.....	472
15.5 Exploring Mbed LPC1768 Power Consumption .....	473
15.5.1 LPC1768 Current Consumption Characteristics.....	474
15.5.2 Controlling Power to Microcontroller Peripherals.....	476
15.5.3 Manipulating the Clock Frequency .....	476
15.5.4 LPC1768 Low-power Modes.....	477
15.5.5 Applying Operating System Sleep Modes.....	477
15.6 Reviewing the Nucleo F401RE Clock and Power Features.....	479
15.7 Getting Serious about Low Power: The M0/M0+ Cores and the Zero Gecko ...	480
Chapter Review .....	482
Quiz.....	483
References.....	484
<b><i>Appendix A: Some Number Systems.....</i></b>	<b>485</b>
<b><i>Appendix B: Some C Essentials, with a Little C++ .....</i></b>	<b>493</b>
<b><i>Appendix C: Mbed LPC1768 Technical Data.....</i></b>	<b>521</b>
<b><i>Appendix D: Parts List .....</i></b>	<b>527</b>
<b><i>Appendix E: Using a Host Terminal Emulator.....</i></b>	<b>531</b>
<b><i>Index.....</i></b>	<b>535</b>

# *Introduction*

It's now eleven years since the first edition of this book was published, and seven years since the second. Microprocessors are of course still everywhere, providing “intelligence” in cars, mobile phones, household and office equipment, TVs and entertainment systems, medical products, aircraft—the list is endless. Those everyday products, where a little computer is hidden inside to add intelligence, are called *embedded systems*.

It is still not so long ago that designers of embedded systems had to be electronics experts, or software experts, or both. Nowadays, with user-friendly and sophisticated building blocks available for our use, both the specialist and the beginner can quickly engage in successful embedded system construction and design. One such building block was the *Mbed*, a self-contained microcontroller development board, launched in 2009 by the renowned computer giant Arm. The Mbed was the central theme of the first edition of this book, and through it all the main topics of embedded system design were introduced.

Technology has continued its onward gallop since those earlier editions, and there is already much from the second edition which needs updating, rewriting, or replacing. The single Mbed device that we based the first book on has spawned an extended family of “Mbed-enabled” devices. An “ecosystem” of products, development tools, and community support has emerged, and the phrase “internet of things” (IoT) is now on everyone's lips. The creators of the Mbed, Arm, repositioned the Mbed concept, notably by placing it at the heart of their IoT developments. The original Mbed LPC1768 device, however, is still there, widely used and well established, in industry, among hobbyists, and in colleges and universities worldwide.

Alongside hardware developments, there has been stunning growth in software techniques. As part of the Mbed ecosystem, Arm have crafted a sophisticated operating system, an essential framework through which program development takes place. While in earlier editions we tried to restrict ourselves more or less to use of the C programming language, this is now no longer possible. The Mbed operating system requires some use of C++, as more advanced applications are encountered.



In light of all these changes, we as authors made a number of decisions regarding this new edition. We have retained the Mbed LPC1768, but recognize that it's approaching the end of its working life. Therefore, in parallel, we've introduced an alternative board, the Nucleo F401RE. You can work through the first 10 chapters of the book using either of these. As if two boards aren't enough, we introduce a third, the ST IoT discovery kit. We use this primarily for [Chapters 11–13](#), the IoT part of the book.

In terms of content, we have dropped the audio and internet chapters to make way for a pair of explicitly IoT-focused chapters. There is also a completely new chapter on using the real time operating system, or RTOS.

Broadly, the book divides into three parts. [Chapters 1 to 10](#) provide a wide-ranging introduction to embedded systems. These chapters aim to give full support to the reader, moving you through a carefully constructed series of concepts and exercises. They start from basic principles and simple projects, and move on to more advanced system design. The next three chapters, 11–13, sit clearly in the realm of wireless and the IoT. They start with the essential wireless techniques which underlie IoT capability, before building up a complex IoT example, linking sensors through intermediate devices right up to the cloud and back! Programming here also includes some Java and JavaScript. The final two chapters, mainly based on the Mbed LPC1768 but not depending on it, look inside the microcontroller to cover more advanced or specialist topics. They explain how some of the most fundamental microcontroller activities are undertaken and how they can be controlled—for example, setting clock speed or optimizing power consumption.

All this book asks of you at the very beginning is a basic grasp of electrical/electronic theory. The book adopts a “learning through doing” approach. To get started, you will need either the LPC1768 or the F401RE development board, an internet-connected computer, and at least some of the various additional electronic components identified. You won't need every single one of these if you choose not to do a certain experiment or book section. You'll also need a digital voltmeter, and ideally use of an oscilloscope.

Each chapter is based on a major topic in embedded systems. Each has some theoretical introduction, and may have more theory within the chapter. Most chapters then proceed as series of practical experiments. Have your board ready to connect up the next circuit, and download and compile the next example program. As your confidence grows, so will your creativity and originality; you will start to turn your own ideas into working projects.

You will find that this book rapidly helps you to

- Understand and apply the key aspects of embedded systems,
- Learn from scratch, or develop your skills in embedded C/C++ programming,
- Understand and apply the key aspects of the Arm Mbed operating system,

- Develop your understanding of electronic components and configurations,
- Produce designs and innovations you never thought you were capable of!

If you are a university or college instructor, then this book offers a “complete solution” for your embedded systems course. All three authors are experienced university lecturers, and had your students in mind when writing this book. The book contains a structured sequence of practical and theoretical learning activity. Ideally you should equip every student or student pair with an Mbed development board, prototyping breadboard, and component kit. These are highly portable, so development work is not confined to the college or university lab. Later in the course students will start networking their devices together. PowerPoint presentations for each chapter are available to instructors via the book web site, as well as answers to quiz questions.

Because the need for electronic theory is limited, this book is accessible to disciplines which would not normally aim to take embedded systems. The book is meant to be accessible to Year 1 undergraduates, though we expect it will more often be used in the years which follow. Students are likely to be studying one of the branches of engineering, physics, or computer science. The book will also be of interest to the practicing professional and the hobbyist.

The first ideas for this book came from Rob Toulson. When at Anglia Ruskin University in Cambridge, he started teaching with those new-fangled Mbed devices, working in close cooperation with the Mbed design team at Arm. Tim Wilmshurst—then at the University of Derby—joined to form a writing duo, and together Rob and Tim brought the first two editions to life. Tim then proposed, and has since led, development of the third edition. A new and welcome co-author, Tom Spink, joins the team for this edition. A lecturer in computer science at the University of St Andrews, Tom brings particular expertise in IoT and the software end of things. He and Tim are also authors of Arm Education MOOCs (massive open online courses) on embedded systems and IoT. Rob meanwhile has moved on from academia to become an active entrepreneur in digital music technologies (<https://www.rt60.uk/>), but has continued to play a supporting role in the new edition.

Because Tim has written several books on embedded systems in the past, a few background sections and diagrams have been taken from these and adapted for inclusion in this book. There seemed no point in “reinventing the wheel” where introductory explanations were needed.

This page intentionally left blank

# ***Acknowledgments***

The authors would like to thank staff from Arm, including Donatien Garnier, Robert Iannello, David MacKenzie, and Andy Powers, for support in the development of this edition, and in earlier work on the MOOCs. Thanks also to those who develop and maintain content on the Mbed OS web site (<https://os.Mbed.com/>). We have made repeated use of this site and benefited from the many example programs therein.

We would further like to thank most warmly the following for their comments on draft chapters. They read and evaluated with care and attention, making valued suggestions for improvements to content or code, exposing lurking typos or technical inaccuracy, and brought their shared teaching expertise to how ideas should be presented and should flow. In alphabetical order they are Hammam Alsafrjalani of the University of Miami, Haitham Abu Ghazaleh of Tarleton State University, John Larkin of Whitworth University, Erik Petrich of the University of Oklahoma, and Atoussa Tehrani of Florida International University. Despite the value of these inputs, any errors or weaknesses in the book remain the authors' responsibility!

Thanks to Liz A of [sweetclipart.com](http://sweetclipart.com) for the use of the car image in Figure 1.3.

## ***Companion Web Site***

[www.embedded-knowhow.co.uk](http://www.embedded-knowhow.co.uk)

This page intentionally left blank

# *Essentials of Embedded Systems, and Developing with Mbed*

This page intentionally left blank

# *Embedded Systems, Microcontrollers, and Arm*

## **1.1 Introducing Embedded Systems**

### **1.1.1 What is an Embedded System?**

We are all familiar with the idea of a desktop or laptop computer, and the amazing processing that they can do. These computers are general-purpose; we can get them to do different things at different times, depending on the application or program we run on them. At the very heart of such computers, we would find one or more *microprocessors*, tiny and fantastically complicated electronic circuits that contain the core features of a computer. These are fabricated on a single slice of silicon, called an *integrated circuit* (IC). Some people, particularly those who are not engineers themselves, call these circuits *microchips*, or just *chips*.

What is less familiar to many people is the idea that instead of putting a microprocessor into a general-purpose computer, it can also be placed inside a product which has nothing to do with computing, like a washing machine, toaster, or camera. The microprocessor is then customized to control that product. The computer is there, inside the product; but it can't be seen, and the user probably doesn't even know it's there. Moreover, those add-ons which we normally associate with a computer, like a keyboard, screen, or mouse, are nowhere to be seen. We call such products *embedded systems*, because the microprocessor that controls them is embedded inside. Because such a microprocessor is developed to control the device, in many cases those used in embedded systems have different characteristics from the ones used in more general-purpose computing machines. We end up calling these embedded computers *microcontrollers*. Though much less visible than their microprocessor cousins, microcontrollers sell in far greater volume, and their impact has been enormous. To the electronic and system designer they offer huge opportunities.

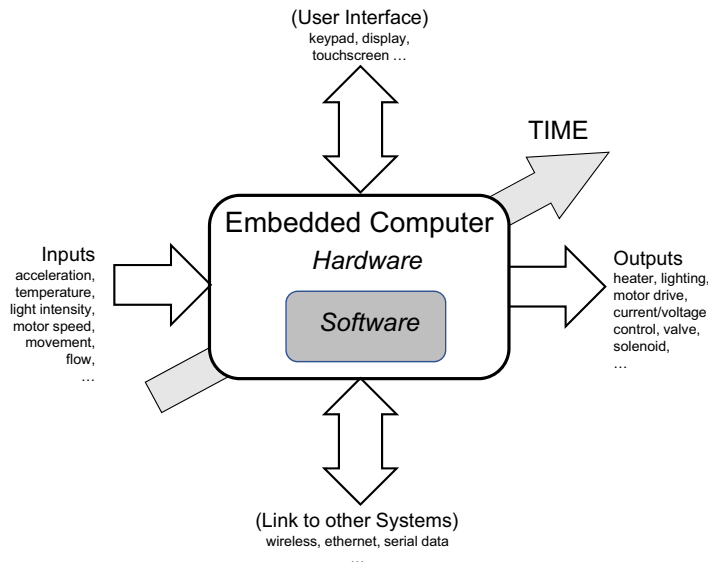
Embedded systems come in many forms and guises. They are extremely common in the home, the motor vehicle, and the workplace. Most modern domestic appliances, like a washing machine, dishwasher, oven, central heating, or burglar alarm, are embedded systems. The motor car is full of them, in engine management, security (e.g., locking and anti-theft devices), crash sensing, air-conditioning, brakes, radio, and so on. They are



found across industry and commerce, in machine control, factory automation, robotics, electronic commerce, and office equipment. The list has almost no end, and it continues to grow.

Fig. 1.1 expresses the embedded system as a simple block diagram. A number of features appear; not every embedded system has all of them. There are one or more inputs from the external environment, for example, sensors providing voltages proportional to physical variables. The embedded computer runs a program dedicated to this application, permanently stored in its memory. Unlike the general-purpose desktop computer, which runs many programs, this is the only program it ever runs. Based on information supplied from the inputs, the microcontroller computes certain outputs, which may be connected to actuators and other devices within the system. Alternatively, that output may simply be data, transferred by cable or wireless to another subsystem elsewhere, or displayed to a user. The user may have further interaction—for example, via a keypad.

The actual electronic circuit, including the microcontroller and any electromechanical components, is often called the *hardware*; the program running on it is often called the *software*. There must be a supply of power to keep the circuits running. One other variable will affect all that we do in embedded systems, and this is time, represented as a dominating arrow which cuts across the figure. We will need to be able to measure time, make things happen at predetermined times, generate data streams or other signals with a strong time dependence, and respond to unexpected things in a timely fashion.



**Figure 1.1**  
The embedded system.

A refrigerator controller provides us with an initial embedded system example. This has a temperature sensor in the main fridge compartment and one in the freezer. The user selects the required temperature or depends on default settings. Meanwhile, sensors are measuring the temperature in each fridge compartment. The embedded computer, a microcontroller, receives incoming signals from the sensors and control setting, compares these, and determines whether the compressor should be switched on or not. It will also display to the user the two temperatures measured, and may emit an alarm if a door is left open too long, or the temperature rises above a certain limit. In its traditional form the fridge does not have any external connection. However, a modern fridge may well be able to connect to the internet, so that the homeowner can check on its status while away—but more on this later.

### ***1.1.2 Fast Forward to the Internet of Things***

General-purpose computers, and now embedded systems, have become increasingly connected to the internet. The Internet of Things (IoT) is the name given to the resultant worldwide network of devices and artefacts—some everyday, some highly specialized—that are connected to the internet. These allow remote access to information that can be used to control and enhance diverse activities. The IoT generates huge quantities of real-time data that can potentially be accessed from anywhere in the world. IoT data now includes billions of sensors and databases that are made available for monitoring through the internet, from travel and transport data to environmental, medical, and industrial concerns large and small.

An integral part of the IoT is the concept of *cloud computing*, which uses servers and data memory storage locations that are only accessed through the internet. Companies such as Google, Microsoft, Apple, and Dropbox, among many others, provide their own cloud-based services, and it is anticipated that most, if not all, of our personal and professional data (and programs) will one day be stored in the cloud rather than on local computers and hard drives.

The IoT concept has expanded to include everyday objects attached to the internet. Examples include a washing machine that can alert the repair company to an impending fault, a vending machine that can tell the head office it is empty, a manufacturer who can download a new version of firmware to an installed burglar alarm, or a homeowner who can switch on the oven from the office or check that the garage door is closed.

### ***1.1.3 The Electric Car—An Abundance of Embedded Systems***

Technical developments in cars have been one of the driving forces behind the growth of embedded systems, with microcontrollers being applied in engine management, braking,

diagnostics, and many other things. Perhaps nowhere has this outpouring of embedded control been more evident than in the modern electric vehicle (EV), with battery replacing gas tank, and DC (direct current) electric motors replacing the internal combustion engine (see Fig. 1.2). Such a vehicle represents an excellent opportunity to apply and exploit embedded systems, using those little microcontrollers to their best advantage.

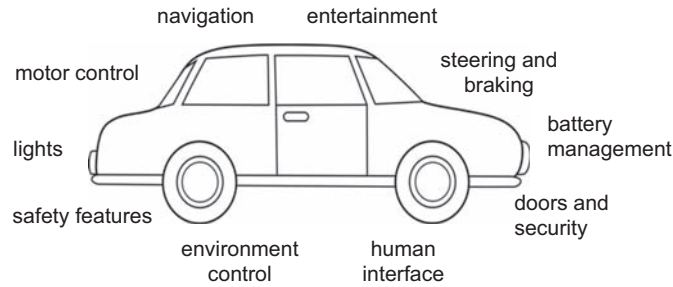
The possible categories of electronic control in the EV are shown in Fig. 1.3. Most of these will overlap, and other categorizations could be made. Each category contains numerous embedded systems, some controlling one or few variables, others managing a sophisticated array.

Imagine Fig. 1.1 implemented dozens of times within the EV, and think of the sensors and actuators in operation. The battery management will need to sense battery voltage and current, sometimes current flowing from battery to motors, at other times from motors back to battery due to kinetic energy recovery, then from charge point to battery when charging is taking place. Safety features will detect closure of seat belts in occupied seats, tire pressure, nearness of vehicle to potential obstacles, and lane following on a motorway or freeway. Environment control will sense internal and external temperatures and the temperature demanded by the driver and manage seat heating. Within most of these are actuators moving, heating, or lighting things they control. There is also an enormous flow of data, within and between the subsystems.



**Figure 1.2**

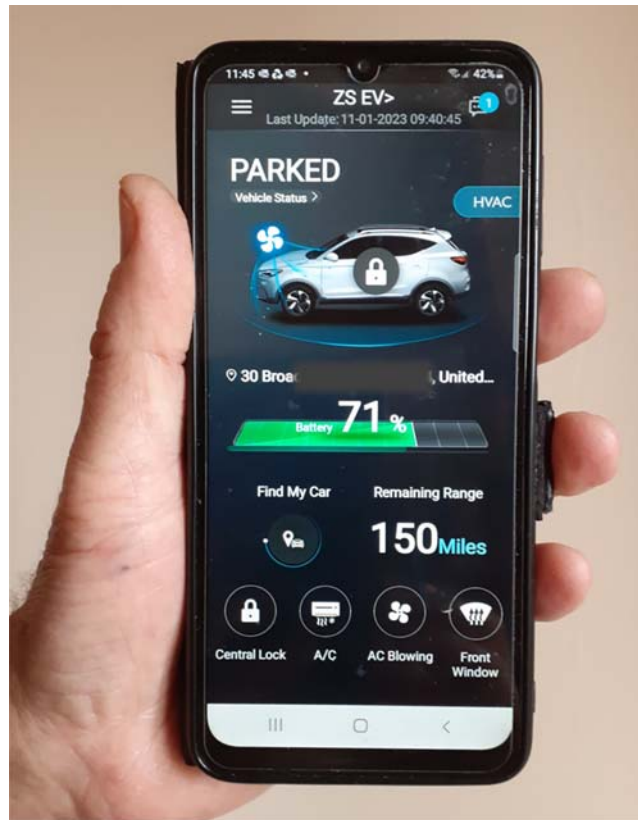
The electric car, rich in embedded systems.



**Figure 1.3**

Electronic subsystems in the electric car.

Needless to say, data generated in the vehicle does not all stay within it. The owner is encouraged—indeed it’s almost a necessity—to download a car-specific phone app, as seen in [Fig. 1.4](#). This tells him or her many things, including the important features of whether the car is locked, the state of battery charge and available driving range, the



**Figure 1.4**

An electric car app.

vehicle state of health, and its location. From it the user can—if a charging cable is connected—start or stop charging. Also, on a cold day, the heating can be started and the windshield de-iced before a journey starts.

The actions just described place us firmly in the realm of the IoT. Data from the car has been transmitted wirelessly to the web, processed, and returned to the app, to be displayed in user-friendly form. Control data generated by the user with the app is then returned to the car for actuation.

This book takes us on a journey which—on completion—should allow you, the reader, to feel able to understand, apply, and even design the circuits and software found in embedded systems large and small. As each new chapter opens, we start at the beginning of that topic, initially with simple concepts.

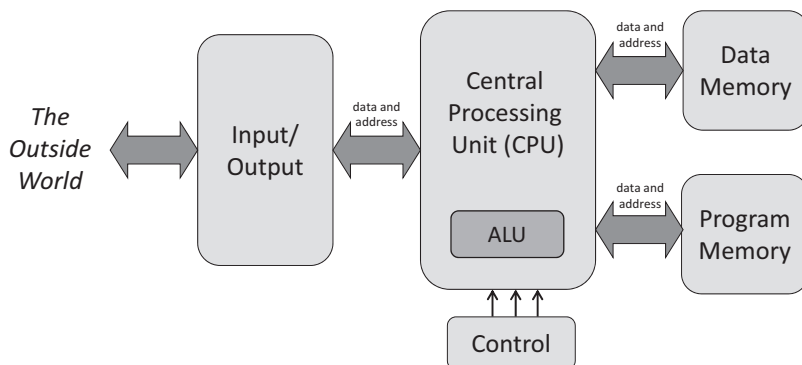
This first chapter introduces or reviews many concepts relating to computers and embedded systems. It does this in overview form, to give a platform for further learning. We return to these concepts in later chapters, building on them and adding detail.

## 1.2 Microprocessors and Microcontrollers

Let's look more closely at the microcontroller, which sits at the heart of any embedded system. As the microcontroller is in essence a type of computer, it will be useful to get a grasp of basic computer details.

### 1.2.1 Some Computer Essentials

Fig. 1.5 shows the essential elements of any computer system. As its very purpose for existence, a computer can perform arithmetic or logical calculations. It does this in a



**Figure 1.5**  
Essentials of a computer.