JOHN D. LENK

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Simplified Design of Microprocessor-Supervisory Circuits

John D. Lenk

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Greetings from the Villa Buttercup!

To my wonderful wife, Irene: Thank you for being by my side all these years! To my lovely family: Karen, Tom, Brandon, Justin, and Michael. And to our Lambie and Suzzie: Be happy wherever you are! And to my special readers: May good fortune find your doorway, bringing good health and happy things. Thank you for buying my books!

To Karen Speerstra, Jo Gilmore, Duncan Enright, Pam Boiros, Joan Dargan, Philip Shaw, Elizabeth McCarthy, Vickie Edwards, Pam Chester, the Newnes people, the UK people, and the EDN people: A special thanks for making me an international best seller, again (this is book 90).

Abundance!

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Preface

This book has something for everyone involved in electronics. No matter what your skill level, this book shows you how to design and experiment with microprocessor-supervisory circuits and interfaces.

For experimenters, students, and serious hobbyists, the book provides sufficient information to design and build microprocessor-supervisory circuits from scratch. The design approach is the one used in all my best-selling books on simplified and practical design.

If you are a working engineer responsible for designing microprocessor-supervisory circuits or selecting supervisory integrated circuits, the variety of circuit configurations described herein should generally simplify your task. The book describes supervisory circuit designs and covers the most popular forms of supervisory integrated circuits available. Throughout the book, you will find a wealth of information on supervisory integrated circuits and related components.

In this book, design problems start with circuits that can be put to immediate use as is and include guidelines for selecting components. By using the guideline values in experimental circuits, you can produce the desired results (such as microprocessor reset, memory protection, power-fail warning, battery backup, and watchdog) by varying the experimental component values, if necessary.

Chapter 1 is devoted to primary microprocessor-supervisory functions. Such functions are vital to all microprocessor-based systems because the functions include safeguards against system failure.

Chapter 2 discusses simplified design with supervisory integrated circuits used in 5-V digital systems.

Chapter 3 is devoted to simplified design with supervisory integrated circuits used in 3-V and 3.3-V digital systems.

Chapter 4 covers simplified design with supervisory integrated circuits that have on-board chip-enable functions.