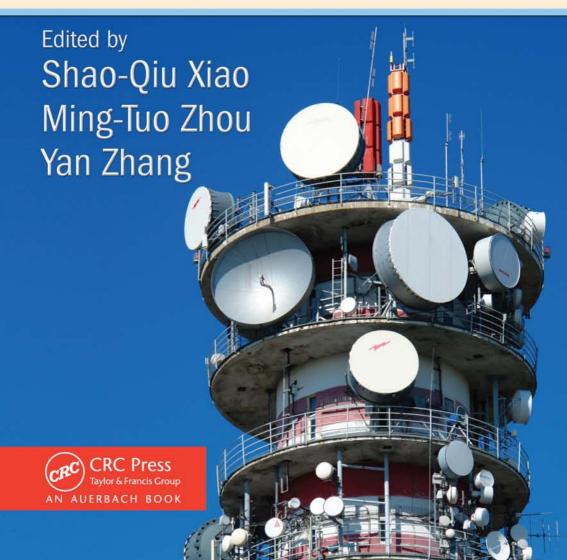
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MILLIMETER WAVE TECHNOLOGY IN WIRELESS PAN, LAN, AND MAN

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MILLIMETER WAVE TECHNOLOGY IN WIRELESS PAN, LAN, AND MAN

Edited by
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Chapter 1

Millimeter-Wave Monolithic Integrated Circuit for Wireless LAN

Jin-Koo Rhee, Dan An, Sung-Chan Kim, and Bok-Hyung Lee

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Introduction 1.1

The increase in high-performance personal computers (PCs) and multimedia equipment in offices and homes requires high-speed and broadband wireless data transmission. This requirement makes wireless indoor communication systems such as wireless local area networks (WLAN) and personal area networks (PAN) because of their portable convenience. For such short-range indoor broadband WLAN and PAN systems, the millimeterwave band offers significant advantages in supplying enough bandwidth for the transmission of various multimedia content. In particular, there has been an increasing requirement for the development of the V-band WLAN for commercial applications. The frequency of 60 GHz is very useful for short-distance wireless communications due to the strong absorption characteristic by oxygen in the atmosphere. Therefore, frequency efficiency is improved compared to other frequency bands. In the last few decades, many research groups in the world have developed millimeter-wave LAN systems. For example, Communications Research Laboratory (CRL, now NiCT) took up the project of developing indoor WLAN systems using millimeter waves in 1992 [1]. The final goal of the millimeter-wave WLAN systems is to provide point-to-multipoint access with transmission rates higher than 100 Mbps for the connectivity of broadband integrated services digital networks (B-ISDNs) or conventional fast Ethernet. For these millimeter-wave WLAN applications, we have to solve some problems. First of all, we have to reduce the size and cost of the systems. The millimeterwave systems are generally fabricated using HIC (hybrid integrated circuit) technology, causing a large system. MMIC (monolithic millimeter-wave integrated circuit) technology is regarded as an alternative to HIC technology due to its ability to integrate active with passive elements on a single semiconductor substrate [2-6]. The MMIC has advantages, such as small size, high reliability, high productivity, and low cost due to using semiconductor technologies compared to the conventional HIC. The main objective of this chapter is to discuss the MMIC technology and its applications for millimeter-wave wireless LAN. First, millimeter-wave WLAN will be introduced. Then, the modeling of active and passive devices will be described. The design and fabrication technologies of millimeter-wave circuits are presented. Finally, millimeter-wave monolithic circuits for WLAN applications are explained.

1.2 Millimeter-Wave Wireless Local Area Network

Recently, a broadband and high-speed indoor network for office and home environments has been required. Additionally, microwave frequency bands have been saturated and there is growing necessity to exploit new frequency bands that have not yet been utilized for commercial applications. For this reason, utilization of the millimeter-wave band has been recommended, and much research has been devoted to developing millimeter-wave wireless LAN. Advantages of millimeter-wave communication are very wide frequency band, high-speed transmission, and radiated power limitation for unlicensed use. Therefore, millimeter-wave WLAN can be utilized in short-range communication and indoor networks. In particular, a 60-GHz band is very useful for wireless short-distance communications due to strong absorption by oxygen. Thus, compared to other frequency bands, frequency efficiency is improved. Figure 1.1 shows the atmospheric absorption versus frequency [7]. Features to be noted are:

- 1. Good coexistence between millimeter-wave system and 802.11a/b/g & Bluetooth due to large frequency difference
- 2. Higher speed transmission, more than 1 Gbps
- 3. Exploitation of antenna directivity
- 4. Simple modulation/demodulation
- 5. Simple signal processing

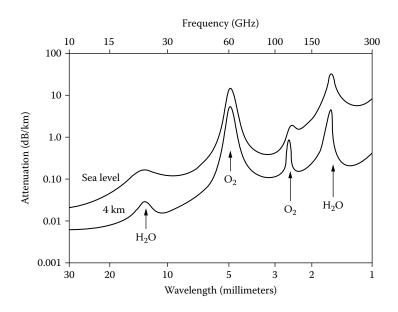
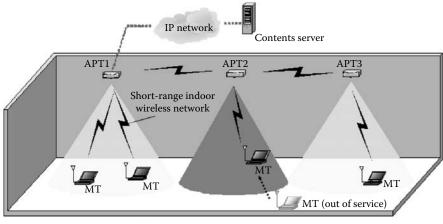


Figure 1.1 Average atmospheric absorption of frequency.



(a) Point-to-point millimeter-wave link

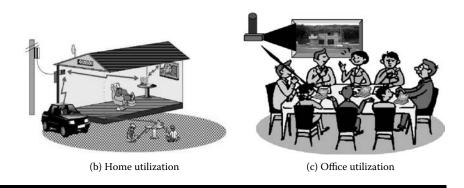


Figure 1.2 Utilizations of millimeter-wave wireless LAN.

Millimeter-wave WLAN is possible for wireless networks such as multimedia equipment, home appliances, videosignal transmissions, and personal computers. Utilization of millimeter-wave WLAN is explained in Figure 1.2. A millimeter-wave circuit and system have been developed using a waveguide module, hybrid integrated circuit method, resulting in large size, high cost, and low productivity. Use of these systems in wireless LAN has many problems due to small size and low cost in wireless LAN. To overcome these problems, high-speed devices such as high electron mobility transistors (HEMTs) and MMTCs need to be added to the millimeter-wave wireless LAN. Figure 1.3 shows normal millimeter-wave WLAN and millimeter-wave circuit components. Millimeter-wave components are usually composed of a low-noise amplifier (LNA), a power amplifier, an oscillator, and an up/down mixer. Also, passive components such as a filter, an antenna, a coupler, and a circulator are required. These components can be varied with system architecture. Millimeter-wave circuits must be

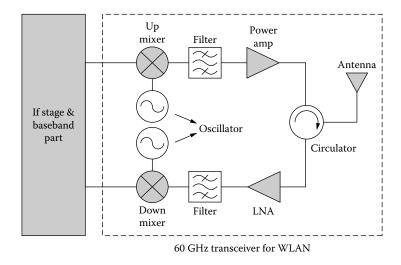


Figure 1.3 Millimeter-wave WLAN and millimeter-wave circuit components (IF, intermediate frequency).

realized high-speed operating characteristics, high linearity, small size, and low cost. For this reason, many technologies such as device modeling, circuit design, circuit fabrication, and measurement technology need to be developed for MMICs.

1.3 Millimeter-Wave Monolithic Integrated Circuit Technology

1.3.1 Millimeter-Wave Device and Modeling

1.3.1.1 Millimeter-Wave HEMT Technology

To fabricate the MMIC devices for the 60-GHz wireless LAN system, the development of active devices that have a high frequency, low noise, and high power performance is an essential theme. Since introduced in 1981 [8], the AlGaAs/GaAs HEMT has been widely used for the microwave region hybrid and monolithic circuits. However, the frequency performances of the conventional AlGaAs/GaAs HEMT devices cannot satisfy the millimeter-wave region (30–300 GHz) MMIC applications. In order to obtain the high-frequency performance, a Pseudomorphic HEMT (PHEMT), which has a relatively low energy band gap characteristic for higher conduction band offset, has been developed. The PHEMT epitaxial structure is shown in Figure 1.4. The epitaxial structure of the device consists of the following layers: an 500 nm GaAs buffer layer, an 18.5/1.5 nm AlGaAs/GaAs × 10 super-lattice buffer layer, a silicon planar doped layer (1×10¹²/cm²), a 6-nm

GaAs capping layer, 5×10^{18} /cm ³ , 30 nm
AIGaAs donor layer, undoped, 25 nm
δ -doping layer, $5 \times 10^{12}/\text{cm}^2$
AIGaAs spacer layer, undoped, 4.5 nm
AIGaAs channel layer, undoped, 12 nm
AIGaAs spacer layer, undoped, 6 nm
δ -doping layer, $1 \times 10^{12}/cm^2$
GaAs super lattice buffer, 500 nm
Semi-insulating GaAs substrate

Figure 1.4 The epitaxial structure for PHEMT fabrication. (Copyright 2004. With permission from Elsevier.)

AlGaAs lower spacer layer, a 12-nm InGaAs channel layer, a 4-nm AlGaAs upper spacer layer, a silicon planar doped layer $(5 \times 10^{12}/\text{cm}^2)$, a 25-nm AlGaAs donor layer, and a 30-nm GaAs cap layer [9-10]. In this chapter, the DC characteristics of the 70 μ m \times 2 PHEMTs were measured by an HP 4156A DC parameter analyzer. The obtained DC performances show a knee voltage (Vk) of 0.6 V, a pinch-off voltage (Vp) of -1.5 V, a drain-source saturation current (Idss) density of 384 mA/mm and a maximum extrinsic transconductance of 367.9 mS/mm, as shown in Figure 1.5. Radio frequency (RF) characteristics of the PHEMTs were examined by an HP 8510C vector network analyzer. The measurement of S-parameters was performed in a frequency range of 1-50 GHz. For this RF measurement, the drain and gate bias conditions of 2 V and -0.6 V were used. We obtained a current gain cutoff frequency (ft) of 113 GHz, a maximum frequency of oscillation (fmax) of 180 GHz, and a measured S21 gain of 3.9 dB at 50 GHz, as shown in Figure 1.6. HEMTs on InP substrates have demonstrated superior microwave and low-noise performances compared to PHEMTs on GaAs substrates. The excellent device performances of the InP-based HEMTs operating in the millimeter-wave region is mostly based on the InGaAs/InAlAs/InP material system. However, compared to GaAs-based wafers, InP-based wafers have some critical drawbacks, such as the mechanical fragility of the wafers and the higher material cost. Moreover, InP-based HEMTs are not quite proper for large-scale production because the backside etching rate for the InP material is much slower. In recent decades, active research has been done on GaAs-based metamorphic HEMTs (MHEMTs) to address the needs for both high microwave performance and low device cost [11-13]. The use of metamorphic buffers on GaAs substrates was introduced to accommodate the lattice mismatch between the substrate and the active layers, as

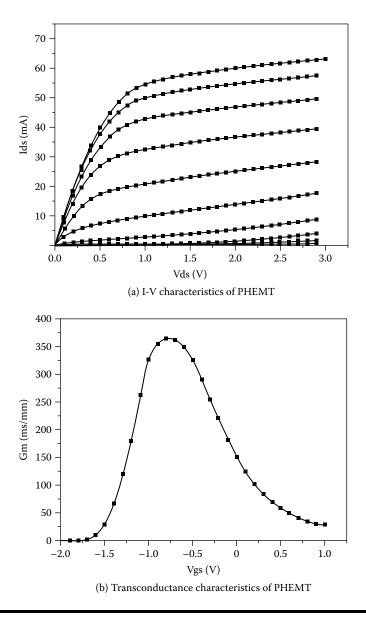


Figure 1.5 DC characteristics of GaAs pseudomorphic HEMT (gate length: 0.1 μ m, total gate width: 140 μ m). (Copyright 2004. With permission from Elsevier.)

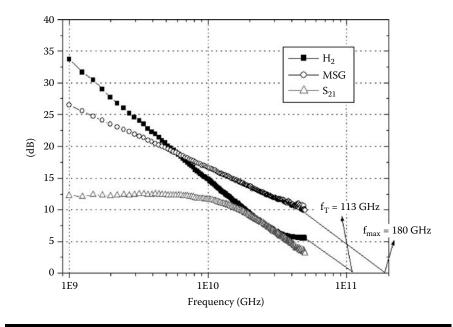


Figure 1.6 The RF characteristics of pseudomorphic HEMT (gate length: 0.1 μ m, total gate width: 140 μ m). (Copyright 2004. With permission from Elsevier.)

well as to avoid the InP substrates. By using the metamorphic buffers, unstrained InGaAs/InAlAs hetero-structures could be grown over a wide range of indium (In) contents for the InGaAs channels, thereby exhibiting device performances comparable to those of InP-based HEMTs. In Figure 1.7, the device active layers of MHEMT are grown on a strain-relaxed, compositionally graded, metamorphic buffer layer. The buffer layer provides the ability to adjust the lattice constant to any indium content channel desired, and therefore allows the device designer an additional degree of freedom to optimize the transistors for high frequency gain, power, linearity, and low noise and to trap dislocations and prevent them from propagating into the device channel. The DC and transfer characteristics of the MHEMT were measured using an HP 4156A semiconductor parameter analyzer. As shown in Figure 1.8, a pinch-off voltage of -1.5 V and a drain saturation current of 96 mA were measured at a gate voltage (Vgs) of 0 V. The fabricated MHEMT also showed a maximum transconductance of 760 mS/mm at a Vgs of -0.3 V and a drain voltage (Vds) of 1.8 V. The S-parameters of the MHEMTs were measured using an ME7808A Vector Network Analyzer in a frequency range from 0.04 to 110 GHz. In Figure 1.9, we showed the measured S21, h21, and maximum stable gain (MSG) of the MHEMT. The measured S21, ft, and fmax of the MHEMT were 6 dB (at 110 GHz), 195 GHz, and 391 GHz, respectively.

InGaAs capping layer, 6×10^{18} /cm ³ , 15 nm
InAIAs donor layer, undoped, 15 nm
δ -doping layer, $4.5 \times 10^{12}/cm^2$
InAIAs spacer layer, undoped, 3 nm
InGaAs channel layer, undoped, 23 nm
InAIAs spacer layer, undoped, 4 nm
δ -doping layer, $1.3 \times 10^{12}/cm^2$
InAIAs buffer layer, undoped, 400 nm
$In_xAI_{1-x}As$ (x = 0~0.5) Metamorphic buffer, undoped, 1000 nm
Semi-insulating GaAs substrate

Figure 1.7 The epitaxial structure for MHEMT fabrication.

1.3.1.2 Millimeter-Wave Active Device Modeling

A small-signal equivalent model is widely used to analyze the characteristics of gains and noises of active devices. These models provide a vital connection between measured S-parameters and the electrical operating characteristics of the device. A more precise small-signal model provides some of the most important information in designing the devices and circuits as well. The components in the small-signal equivalent circuit are composed of a lumped element approximation to some aspect of the device physics. The small-signal equivalent model consists of both extrinsic and intrinsic elements. In general, the operating characteristics of devices may be mainly decided by the intrinsic elements such as Cgs, Cgd, Cds, gm, gds, and Ri. The values of intrinsic elements may be varied by the values of extrinsic elements. Therefore, through the precise extraction of the values of extrinsic elements, a more precise small-signal equivalent model may be formed. The small-signal parameter extraction of the HEMT is very useful for the device modeling and analysis in the design of millimeter-wave circuits. The small-signal equivalent circuit of an HEMT is shown in Figure 1.10. Basically, this equivalent circuit can be divided into two parts: (1) the intrinsic elements gm, Rds, Cgs, Cgd, Cds, Ri, and which are functions of the biasing conditions; and (2) the extrinsic elements Lg, Ld, Ls, Rg, Rd, Rs, Cpg, and Cpd, which are independent of the biasing conditions.

The extraction method of small-signal parameters has usually used the Dambrine method [14]. Figure 1.11 and Table 1.1 show the procedure of small-signal extraction and the extracted small-signal parameters of normal GaAs HEMTs, respectively. A small-signal model depicts linear characteristics of the device, while a large-signal model expresses nonlinear

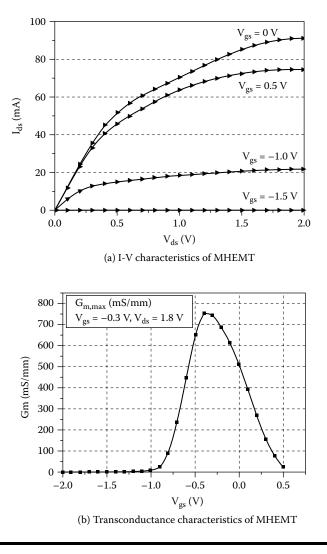


Figure 1.8 DC characteristics of GaAs metamorphic HEMT (gate length: 0.1 μ m, total gate width: 140 μ m).

characteristics of the device. Analytical large-signal models approximate the nonlinear properties of an active device using a unique set of analytical equations. These nonlinear characteristics can be related to elements of the large-signal equivalent circuit. The large-signal parameters and the equivalent circuit are shown in Table 1.2 and Figure 1.12 respectively [15]. The large-signal model of the device can be used to analyze the performance of the nonlinear components, such as a power amplifier, an oscillator, a mixer, etc. Several studies have developed a large-signal model that

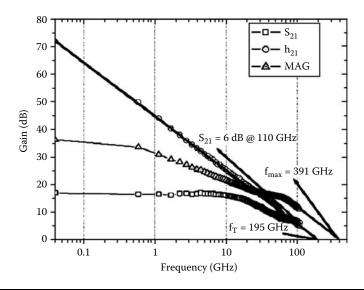


Figure 1.9 The RF characteristics of metamorphic HEMT (gate length: 0.1 μ m, total gate width: 140 μ m).

describes the nonlinear characteristics of a device. These models include the Curtice model, Statz model, TriQuint Own Model (TOM), Root, etc. The large-signal modeling method is generally following procedures and is shown in Figure 1.13: (1) device measurement (DC, RF characteristics), (2) extraction of parameter set using analytical equations, (3) a simulation

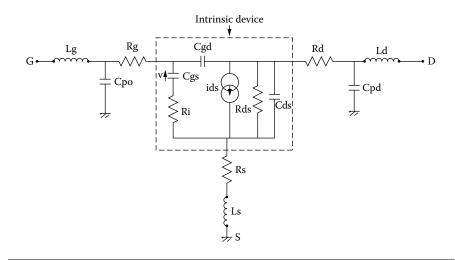


Figure 1.10 A small-signal equivalent circuit of HEMT.

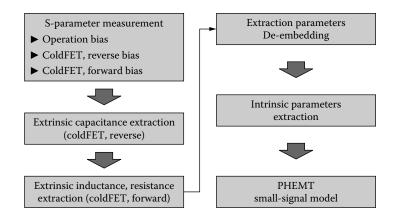


Figure 1.11 The procedure of small-signal modeling.

Table 1.1 The Extracted Small-Signal Parameters of GaAs, PHEMTs, and MHEMTs (gate length: 0.1 μ m; total gate width: 140 μ m)

Extrinsic		Intrinsic	
Parameter	Value	Parameter	Value
(a) GaAs Ps	seudomorp	bic HEMT	
$R_g [\Omega]$	1.980	C _{gs} [pF]	0.178
$R_d^{\circ}[\Omega]$	6.900	C _{gd} [pF]	0.010
$R_s [\Omega]$	3.120	C _{ds} [pF]	0.012
L _g [nH]	0.085	$R_{ds} [\Omega]$	782.2
$L_{d}^{"}$ [nH]	0.140	G_m [mS]	58.59
L _s [nH]	0.011	τ [psec]	1.190
C _{pg} [pF[0.060	$R_i [\Omega]$	2.310
C _{pd} [pF]	0.040		
(b) GaAs Mo	etamorphic	HEMT	
$R_g [\Omega]$	2.560	C_{gs} [pF]	0.062
$R_d^{\circ}[\Omega]$	6.730	C _{gd} [pF]	0.005
$R_s [\Omega]$	2.600	C _{ds} [pF]	0.003
L _g [nH]	0.210	$R_{ds} [\Omega]$	1143
$L_{d}^{"}$ [nH]	0.094	G_m [mS]	83.73
L _s [nH]	0.006	τ[psec]	1.030
C _{pg} [pF[0.054	$R_i [\Omega]$	1.720
C _{pd} [pF]	0.052		

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Table

Zero-bias threshold parameter Gate-source voltage where transconductance is maximum Peak transconductance parameter Drain-source current saturation parameter Output conductance parameter Maximum input capacitance for Vds = Vdso and Vdso > Deltds Minimum input capacitance for Vds = Vdso and Vdso > Deltds Inflection point in C11-Vgs characteristic C11th to C11 ot transition voltage Linear region to saturation region transition parameter C11th to C11 ot transcitors slope parameter Linear region to saturation region transition parameter C11th to C3 control in C11-Vgs characteristics slope parameter C11th to C11 ot transcitors slope of transconductance compression transition voltage C11th to C11 ot transcitors transcion transition parameter C11th to C11 ot transcion transcion transition parameter C11th to C11 ot	Parameter	Description	PHEMT (Unit)	MHEMT (Unit)
Gate-source voltage where transconductance is maximum ax Peak transconductance parameter Drain-source current saturation parameter Output conductance parameter Output conductance parameter Drain-source current saturation parameter C11 th to C11 o transition voltage Linear region to saturation region transition parameter C11 th to C11 o transition voltage Linear region to saturation region transition parameter C11 voltace characteristics slope parameter C12 voltace characteristics slope parameter C13 voltace characteristics slope parameter C14 voltace characteristics slope parameter C15 voltace capacitance for Vgs = Vinfl and Vds > Deltds C17 voltace characteristics slope parameter C17 voltace capacitance of voltace voltace capacitance Dispersion source cuput impedance Dispersion source capacitance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance parameter (AC) Dispersion source capacitance (AC) Additional d—b branch conductance compression begins C11 voltage where transconductance compression voltage C12 voltage where transconductance compression voltage C13 voltage voltace voltace compression characteristic C14 voltage voltance compression characteristic C15 voltage voltance compression characteristic C16 voltage voltance compression characteristic C17 voltage voltance voltance compression characteristic C17 voltage voltage voltage voltage C17 voltage voltage voltage voltage v	Vto	Zero-bias threshold parameter	-1.679 (V)	-1.237 (V)
ax Peak transconductance parameter Drain-source current saturation parameter Output conductance parameter Output conductance parameter Output conductance parameter Maximum input capacitance for Vds = Vdso and Vdso > Deltds Linear region to saturation voltage Linear region to saturation region transition parameter C11 th to C11 o transition voltage Linear region to saturation region transition parameter C11 Vds characteristics slope parameter C12 Vds C13 Vds C14 Vds C14 Vds C14 Vds C15 Vds C15 Vds C17	Vgo	Gate-source voltage where transconductance is maximum	-634.2 (mV)	-687.0 (mV)
Drain-source current saturation parameter Output conductance parameter Maximum input capacitance for Vds = Vdso and Vdso > Deltds Minimum input capacitance for Vds = Vdso Minimum input capacitance for Vds = Vdso Inflection point in C11-Vgs characteristic C11th to C11o transition voltage C11-Vds characteristics slope parameter Intercept or Vds > Deltds C11-Vds characteristics slope parameter C11-Vds characteristics slope slope of transconductance compression fransition parameter C11-Vds characteristics slope of transconductance saturation-to-compression transition parameter C11-Vds characteristics slope of transconductance saturation-to-compression transconduc	Gm, max	Peak transconductance parameter	46.83 (mS)	76.21 (mS)
Output conductance parameter Maximum input capacitance for Vds = Vdso and Vdso > Deltds Minimum input capacitance for Vds = Vdso Inflection point in C11-Vgs characteristic Inflection point in C11-Vgs characteristic Inflection point in C11-Vgs characteristic C11th to C11o transition voltage Inflection point in C11-Vgs characteristic C11th to C11o transition voltage Inflection point in C11-Vgs characteristic C11th to C11o transition voltage C11-Vds characteristics slope parameter Inflection point in C11-Vgs characteristic C11-Vds characteristics slope parameter Inflection point in C11-Vgs characteristic C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter C11-Vds characteristics C11-Vds characteristics C11-Vds characteristics C11-Vds characteristics C11-Vds characteristic C11-Vds characteristics C11-Vds characteristic C11-Vds c11-Vds characteristic C11-Vds c11-Vds c11-Vds characteristic C11-Vds c11-V	Vsat	Drain-source current saturation parameter	973.0 (mV)	193.2.0 (mV)
Maximum input capacitance for Vds = Vdso and Vdso > Deltds 129.2 (ff) Minimum input capacitance for Vds = Vdso 11.20 (V) C11th to C11 otransition voltage 11.831 (V) Linear region to saturation region transition parameter 11.831 (V) Linear region to saturation region transition parameter 11.831 (V) Linear region to saturation region transition parameter 11.831 (V) Linear region to saturation region transition parameter 11.831 (V) C11-Vds characteristics slope parameter 20.46 (ff) Cate-drain capacitance for Vds = Volfds 15.20 (ff) Drain-source inter-electrode capacitance 15.20 (ff) Drain-source inter-electrode capacitance 15.20 (ff) Dispersion source capacitance 15.20 (ff) Dispersion source capacitance 15.20 (ff) Additional d—b branch conductance at Vds = Vdsm 15.20 (ff) Additional d—b branch conductance at Vds = Vdsm 15.20 (ff) Additional d—b branch conductance of a conductance compression begins 15.70 (ff) Caro-bias threshold parameter (AC) 15.75 (M) Channel-to-backside self-heating parameter (AC) 15.75 (M) Channel-to-backside self-heating parameter (AC) 15.75 (M) Additional dadds Vds dependence to transconductance compression (fill mensionless) Lansconductance compression (fill fransition voltage 267.2 (mS/N) Transconductance compression transition parameter 2.094 (V) Transconductance saturation-to-compression transition parameter 2.094 (V)	Карра	Output conductance parameter	0.013 (1/V)	0.025 (1/V)
Minimum input capacitance for Vds = Vdso Inflection point in C11-Vgs characteristic C11th to C11o transition voltage C11th to C11o transition voltage Linear region to saturation region transition parameter C11-Vds characteristics slope parameter C12-Vds characteristics slope parameter C23-Viff and Vds > Deltds C348 (1/V) C40-Vd (F) C4	C110	Maximum input capacitance for $Vds = Vdso$ and $Vdso > Deltds$	129.2 (fF)	72.4(fF)
Inflection point in C11-Vgs characteristic C11th to C11o transition voltage C11th to C11o transition voltage C11th to C11o transition voltage C11-Vds characteristics slope parameter Cate-drain capacitance for Vgs = Vinfl and Vds > Deltds Dispersion source output impedance Dispersion source capacitance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance parameter (AC) Additional d—b branch conductance parameter (AC) Additional d—b branch conductance parameter (AC) Caro-bias threshold parameter (AC) Caro-bias threshold parameter (AC) Caro-bias threshold parameter (AC) Caro-bias threshold parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Arameter that adds Vds dependence to transconductance compression "tail-off" parameter Tansconductance compression characteristic Transconductance roll-off to tail-off transition voltage Slope of transconductance compression transition parameter C11th (MV) Transconductance saturation-to-compression transition parameter C11th (MV) Transconductance saturation-to-compression transition parameter C11th (MV) Transconductance saturation-to-compression transition parameter C11th (MV) Transconductance squration-to-compression transition parameter C11th (MV) Transconductance squration-to-compression transition parameter C11th (MV) Transconductance squration-to-compression transition parameter	C11th	Minimum input capacitance for $Vds = Vdso$	184.9 (aF)	67.57 (aF)
C11th to C11o transition voltage Linear region to saturation region transition parameter C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter Input transcapacitance for Vds > Deltds Cate-drain capacitance for Vds > Deltds Drain-source inter-electrode capacitance Dispersion source output impedance Dispersion source capacitance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Zero-bias threshold parameter (AC) Cutput conductance parameter (AC) Cutput conductance parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside dependence to transconductance compression "tall-off" parameter Transconductance compression characteristic Transconductance saturation-to-compression transition parameter Transconductance saturation-to-compression transition parameter Transconductance saturation-to-compression transition parameter Transconductance saturation-to-compression transition parameter Transconductance compression transition parameter Transconductance compression transition parameter Transconductance saturation-to-compression transition parameter Transconductance compression transition to transconductance compression transition parameter Transconductance compression transition to transconductance compression transition transconductance compression transconductance compression t	Vinfl	Inflection point in C11-Vgs characteristic	-1.120 (V)	-1.958 (V)
Linear region to saturation region transition parameter C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter C11-Vds characteristics slope parameter Cate-drain capacitance for Vds > Deltds Cate-drain capacitance for Vds > Deltds Drain-source inter-electrode capacitance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Peak transconductance parameter (AC) Zero-bias threshold parameter (AC) Zero-bias threshold parameter (AC) Channel-to-backside self-heating parameter (AC) Coutput conductance compression "tansition parameter (TW) Coutput conductance compression characteristic Coutput conductance compression characteristic Coutput conductance compression characteristic Coutput conductance compression characteristic Coutput conductance couppus conductance compression (FF) Coutput conductance compre	Deltgs		11.831 (V)	12.071 (V)
c C11-Vds characteristics slope parameter Input transcapacitance for Vds = Vinfl and Vds > Deltds Gate-drain capacitance for Vds > Deltds Gate-drain capacitance for Vds > Deltds Gate-drain capacitance Dispersion source output impedance Dispersion source capacitance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance parameter (AC) Zero-bias threshold parameter (AC) Caro-bias threshold parameter (AC) Coutput conductance parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter Transconductance compression "tail-off" parameter Transconductance compression characteristic Slope of transconductance compression characteristic Transconductance saturation-to-compression transition parameter	Deltds	Linear region to saturation region transition parameter	1.103 (V)	0.160 (V)
Input transcapacitance for Vgs = Vinfl and Vds > Deltds Gate-drain capacitance for Vds > Deltds Gate-drain capacitance for Vds > Deltds Dispersion source output impedance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Peak transconductance parameter (AC) Zero-bias threshold parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter Channel-to-backside self-heating parameter Channel-to-backside self-heating parameter Transconductance compression begins Parameter that adds Vds dependence to transconductance compression Transconductance conpression characteristic Slope of transconductance compression characteristic Transconductance saturation-to-compression transition parameter 2.094 (V)	Lambda	C11-Vds characteristics slope parameter	0.348 (1/V)	0.696 (1/V)
Gate-drain capacitance for Vds > Deltds Drain-source inter-electrode capacitance Dispersion source output impedance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance parameter (AC) Zero-bias threshold parameter (AC) Channel-to-backside self-heating parameter (AC) Channel (AC) Channel (AC) Channel (AC) Channel (C12sat	Input transcapacitance for $Vgs = Vinfl$ and $Vds > Deltds$	20.46 (fF)	5.934 (fF)
Drain-source inter-electrode capacitance Dispersion source output impedance Dispersion source capacitance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance parameter (AC) Zero-bias threshold parameter (AC) ac Output conductance parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backsid	Cgdsat	Gate-drain capacitance for Vds > Deltds	15.40 (fF)	21.77(fF)
Dispersion source output impedance Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance parameter (AC) Zero-bias threshold parameter (AC) ac Output conductance parameter (AC) Channel-to-backside self-heating parameter Channel-to-backside self-heating parameter (AC)	Cdso	Drain-source inter-electrode capacitance	15.20 (fF)	20.48 (aF)
Dispersion source capacitance Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance at Vds = Vdsm Peak transconductance parameter (AC) Caro-bias threshold parameter (AC) ac Vds-dependent threshold parameter (AC) Channel-to-backside self-heating parameter (AC) Tansconductance compression "tail-off" parameter Tool (V) Transconductance compression characteristic Slope of transconductance compression transition parameter Tansconductance saturation-to-compression transition parameter 2.094 (V)	Rdb	Dispersion source output impedance	1,000 (Gohms)	1.300 (Gohms)
Additional d—b branch conductance at Vds = Vdsm Additional d—b branch conductance at Vds = Vdsm Peak transconductance parameter (AC) ac Output conductance parameter (AC) Channel-to-backside self-heating parameter (AC) Tansconductance compression "tail-off" parameter Transconductance compression characteristic Slope of transconductance compression transition parameter Transconductance saturation-to-compression transition parameter 2.094 (V)	Cds	Dispersion source capacitance	160.0 (fF)	183.0 (fF)
axac Peak transconductance parameter (AC) Zero-bias threshold parameter (AC) aac Vds-dependent threshold parameter (AC) abcording a where transconductance compression begins Parameter that adds Vds dependence to transconductance compression Transconductance compression characteristic Transconductance compression characteristic Slope of transconductance compression characteristic Transconductance compression characteristic Transconductance compression characteristic Transconductance saturation-to-compression transition parameter 2.094 (V)	Gdbm	Additional d—b branch conductance at Vds = Vdsm	51.31 (uS)	50.87 (uS)
Zero-bias threshold parameter (AC)	Gmmaxac	Peak transconductance parameter (AC)	42.57 (mS)	63.81 (mS)
ac Vds-dependent threshold parameter (AC) ac Output conductance parameter (AC) ac Output conductance parameter (AC) Channel-to-backside self-heating parameter (AC) Voltage where transconductance compression begins Parameter that adds Vds dependence to transconductance compression "tail-off" parameter Transconductance compression valial-off transition voltage Transconductance compression characteristic Slope of transconductance compression transition parameter Transconductance saturation-to-compression transition parameter 2.094 (V)	Vtoac	Zero-bias threshold parameter (AC)	-1.703 (V)	-2.376 (V)
channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Channel-to-backside self-heating parameter (AC) Voltage where transconductance compression begins Parameter that adds Vds dependence to transconductance compression "tail-off" parameter Transconductance compression "tail-off transition voltage Transconductance compression characteristic Slope of transconductance saturation-to-compression transition parameter 207.2 (mS/V) Transconductance saturation-to-compression transition parameter	Gammaac	Vds-dependent threshold parameter (AC)	35.14 (mS)	43.63 (mS)
Channel-to-backside self-heating parameter (AC) 15.75 (W) Voltage where transconductance compression begins Parameter that adds Vds dependence to transconductance compression "tail-off" parameter Transconductance compression "tail-off transition voltage Slope of transconductance compression characteristic 267.2 (mS/V) Transconductance saturation-to-compression transition parameter 2.094 (V)	Карраас	Output conductance parameter (AC)	65.13u (1/V)	67.25u (1/V)
Voltage where transconductance compression begins —660.2 (mV) Parameter that adds Vds dependence to transconductance compression 0.0024 (dimensionless) Transconductance compression "tail-off" parameter 1.001 (V) Transconductance roll-off to tail-off transition voltage 267.2 (mS/V) Slope of transconductance compression characteristic 267.2 (mS/V) Transconductance saturation-to-compression transition parameter 2.094 (V)	Peffac	Channel-to-backside self-heating parameter (AC)	15.75 (W)	29.56 (W)
Parameter that adds Vds dependence to transconductance compression 0.0024 (dimensionless) Transconductance compression "tail-off" parameter Transconductance roll-off to tail-off transition voltage Slope of transconductance compression characteristic Transconductance saturation-to-compression transition parameter 2.094 (V)	Vco	Voltage where transconductance compression begins	-660.2 (mV)	-1.071 (mV)
Transconductance compression "tail-off" parameter 1.001 (V) Transconductance roll-off to tail-off transition voltage 701.4 (mV) Slope of transconductance compression characteristic 267.2 (mS/V) Transconductance saturation-to-compression transition parameter 2.094 (V)	Mu	Parameter that adds Vds dependence to transconductance compression	0.0024 (dimensionless)	0.0043 (dimensionless)
Transconductance roll-off to tail-off transition voltage Slope of transconductance compression characteristic Transconductance saturation-to-compression transition parameter 2094 (V)	Vba	Transconductance compression "tail-off" parameter	1.001 (V)	1.331 (V)
Slope of transconductance compression characteristic 267.2 (mS/V) Transconductance saturation-to-compression transition parameter 2.094 (V)	Vbc	Transconductance roll-off to tail-off transition voltage	701.4 (mV)	849.8 (mV)
Transconductance saturation-to-compression transition parameter 2.094 (V)	Deltgm		267.2 (mS/V)	51.11 (mS/V)
	Alpha	Transconductance saturation-to-compression transition parameter	2.094 (V)	1.033 (V)

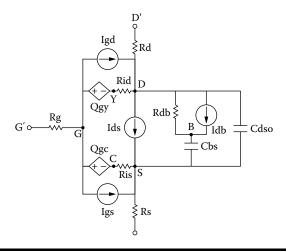


Figure 1.12 The equivalent circuit of an HEMT large-signal model (EEHEMT1 model).

using extracted parameter, (4) a comparison of measured characteristics and simulated characteristics, (5) an optimization of nonlinear. Figure 1.14 shows the comparison of measured and simulated results of a large-signal model (0.1 GaAs MHEMT) in frequency range from 1 to 110 GHz at the gate voltage of -1.0 V and the drain voltage of 1.8 V.

1.3.1.3 Millimeter-Wave Passive Device Modeling

In MMIC design, passive components are used for impedance matching, DC biasing, phase-shifting, and many other functions. These elements include not only the distributed transmission lines such as a coplanar waveguide

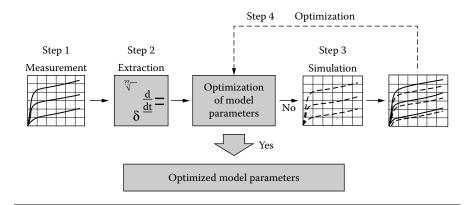


Figure 1.13 The procedure of nonlinear large-signal modeling.

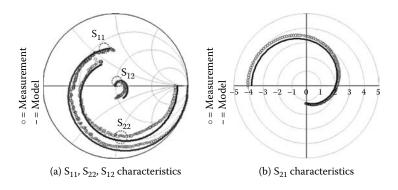


Figure 1.14 The modeling result of GaAs MHEMT (gate length: 0.1 μ m; total gate width: 140 μ m, gate voltage: –1.0 V; drain voltage: 1.8 V; —: model; o: measurement; frequency range: 1 \sim 110 GHz).

(CPW) and a microstrip line but also the lumped capacitors and resistors. In millimeter-wave range, the distributed transmission lines have been mainly used because of low resonance frequency of lumped elements. In this chapter, the CPW structure was employed, because it has many advantages over the microstrip line structure in millimeter wave. It is well known that CPWbased MMIC processes may be cheaper than microstrip-based processes with holes and have high yield because backside processes are not needed [16-20]. Furthermore, CPW structure increases the packing density of the circuit and reduces the substrate dispersion characteristics for millimeterwave operation. Figure 1.15 shows the CPW structure on GaAs substrate. The CPW models include curves, T junctions, and cross junctions as well as common elements, as shown in Figure 1.16. For simulation of the designed CPW, we used commercial software such as LineCalc of ADS from Agilent Incorporated. Figure 1.17 explains the extraction technology of passive device modeling. The passive libraries were finally completed after optimization by comparing the measured S-parameters with the momentumsimulated S-parameters. Metal-insulator-metal (MIM) capacitors and the

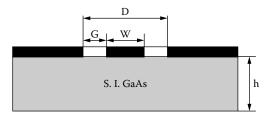


Figure 1.15 The coplanar waveguide (CPW) structure.

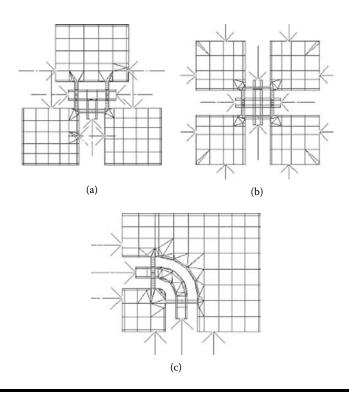


Figure 1.16 The CPW discontinuity patterns for EM analysis: (a) CPW "Tee," (b) CPW cross, and (c) CPW curve.

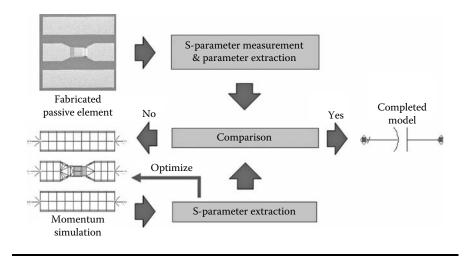


Figure 1.17 The extraction technology of the passive model.

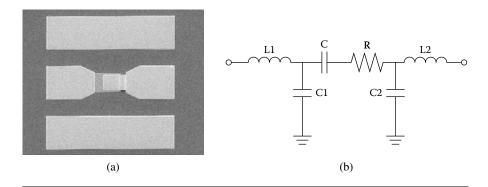


Figure 1.18 The fabricated metal-insulator-metal (MIM) capacitor: (a) the micrograph of the MIM capacitor (capacitor size: 45 μ m \times 45 μ m), and (b) the equivalent circuit of the MIM capacitor.

Ti thin-film resistors were fabricated and modeled. Capacitors are used in MMICs for blocking and bypass purposes. Due to the high dielectric constant (r = 5.5-7.5) and breakdown field (> 106 V/cm), the Si3N4 is mostly preferred as a dielectric layer for MIM capacitors [21]. An Si3N4 film was deposited using the PECVD (plasma-enhanced chemical vapor deposition) system for the MIM capacitor. The connection between the top capacitor plate and adjacent metallization is an airbridge connection in order to avoid problems caused by edges and slopes. The SEM photography of the fabricated MIM capacitor is shown in Figure 1.18(a), and the applied lumped equivalent circuit is shown in Figure 1.18(b). Resistors are used in MMICs for several purposes including feedback, isolation, terminations, and voltage dividers (or self-biasing) in a bias network. Ti thin-film resistors allow precise control of resistance due to their small sheet resistances and have a large current capacity per unit width compared to resistors composed of the active GaAs material [22]. The SEM photography of the fabricated thinfilm resistor is shown in Figure 1.19a, and the applied lumped equivalent circuit is shown in Figure 1.19b.

1.3.2 Design Technology of Millimeter-Wave Monolithic Circuits

In the field of a millimeter-wave monolithic circuit, more detailed design technologies are needed than for a microwave monolithic circuit. These needs can be met only by more accurate circuit simulation both for chip yield and electrical performance due to high frequency. Although an electromagnetic (EM) field analysis was used in millimeter wave, the efficient design method is required because of reduction of simulation time and stable design. The efficient design technology of a millimeter-wave monolithic

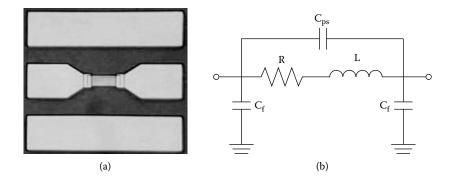
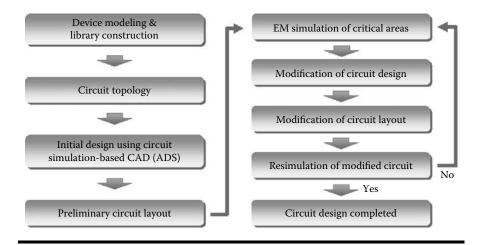


Figure 1.19 The fabricated Ti thin-film resistor: (a) the micrograph of the Ti thinfilm resistor (length of 60 and width of 30) and (b) the equivalent circuit.

circuit is as follows: (1) perform modeling of active and passive devices, (2) determine the circuit topology, (3) perform initial design using circuit simulation based on CAD, (4) perform the preliminary circuit layout, (5) analyze using EM simulation of critical areas, (6) modify the circuit design and layout, (7) perform the resimulation for the modified circuit, (8) optimization through repeating phases (5-7). Figure 1.20 shows the design flow of a millimeter-wave monolithic circuit. Although design of a millimeterwave monolithic circuit is similar to a microwave circuit design in phases 1-5, EM simulation and layout optimization are required due to the parasitic effect for accurate design. However, EM simulation requires a very long time and significant computing capacity, if the total MMIC pattern is



The design procedure of a millimeter-wave monolithic integrated Figure 1.20 circuit.

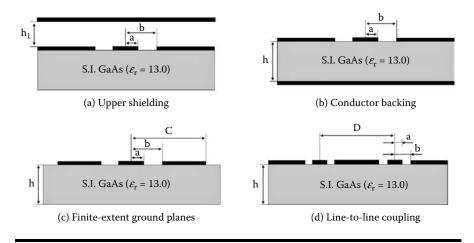


Figure 1.21 Parasitic effects of a CPW transmission line. (Taken from [23] IEEE 1987.)

simulated. Also, it is not easy for a designer to revise the circuit pattern through EM simulation of the total pattern. For design technology to solve this problem, analysis of a basic parasitic effect can be presented [23]. CPW offers several advantages over conventional microstrips for millimeter-wave monolithic circuit applications on GaAs substrates. But, CPW has parasitic effects such as upper shielding, conductor backing, lateral ground plane truncation, and line-to-line coupling. These parasitic effects change MMIC characteristics for various pattern shapes. Figure 1.21 explains the parasitic effects of a CPW transmission line. In millimeter-wave circuit design, some analysis concerning CPW lines on GaAs substrates can be used for the aim of practical design criteria. The effect of upper shielding basically results in a reduction of the line impedance. This is clearly seen in Figure 1.22, where the constant Zol curves are given in the plane a/b h_1/b , while the substrate thickness was set to h/b = 1. Although the minimum cover height needed to avoid significant impedance lowering depends on the line impedance itself, as a conservative estimate the cover height should be at least hl = 4b. As expected, conductor-backed coplanar lines are slightly less sensitive than upper shielding coplanar waveguides for the same characteristic impedance. However, also for this case, the design criterion $h_1 > 3b$ is a conservative estimate. If the minimum substrate thickness needs to be independent of line impedance, then a rough estimate for a 50 line suggests h/b > 3 as a reasonable value (error with respect to h/b $\rightarrow \infty$ less than 2 percent). Figure 1.23 shows constantimpedance conductor-backed coplanar waveguide as a function of the shape ratio a/b. Finite ground-plane width leads to a slight increase of the line impedance with respect to the ideal case ($c \to \infty$, or $b/c \to 0$) as shown in Figure 1.24 (h/b = 1, C/b ranging from 1 to 3.33). In case

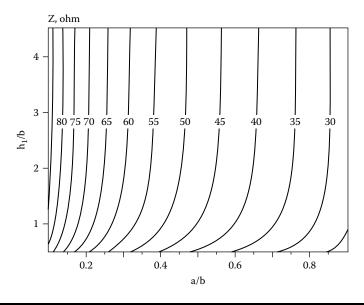


Figure 1.22 Constant impedance with upper shielding coplanar waveguide as a function of the shape ratio, a/b and the cover height, h_I/b , with substrate thickness h/b = 1 and GaAs substrate permittivity $\varepsilon_r = 13$. (Taken from [23] IEEE 1987.)

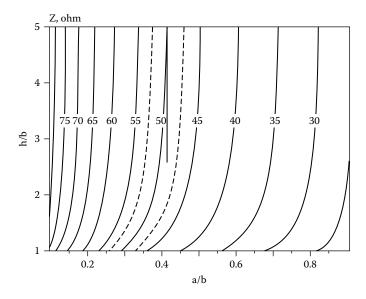


Figure 1.23 Constant-impedance conductor-backed coplanar waveguide without upper shielding as a function of the shape ratio, a/b, and the substrate thickness, h/b, with GaAs substrate permittivity $\varepsilon_r = 13$. (Taken from [23] IEEE 1987.)

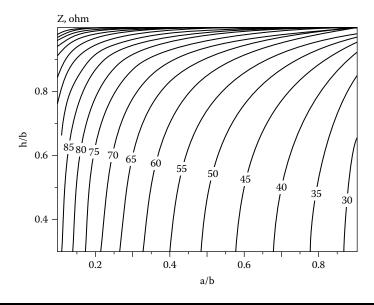


Figure 1.24 Constant-impedance coplanar waveguide with finite ground planes as a function of the shape ratio, a/b, and the inverse of the ground plane width, b/C, with substrate thickness h/b = 1 and GaAs substrate permittivity $\varepsilon_r = 13$. (Taken from [23] IEEE 1987.)

of very narrow lateral ground planes, the impedance is largely increased. As a conservative estimate, one should have C/b = 4 at least to ensure that the variation is negligible. As a last point, let us consider line-to-line coupling. A chart for evaluating this effect is shown in Figure 1.25. It can be seen that coupling weakly depends on the shape ratio a/b, whereas, as is obvious, it is strongly influenced by the line spacing D. From Figure 1.25, the minimum D needed to ensure coupling less than a given value can be obtained. As a conservative estimate of maximum coupling allowed, one can assume, for instance, the value of 40 dB, thereby requiring line spacing to be at least D/b = 7. Based on analysis of the CPW parasitic effect, we can expect a critical area with an electrical characteristic that is very different compared to the result of circuit-based simulation (ideal case). Figure 1.26 shows the preliminary layout of millimeter-wave amplifier and critical areas. Figure 1.27 is an EM simulation pattern for critical areas. The design example is a W-band MMIC amplifier employed in a two-stage structure with 70 μ m \times 2 MHEMTs. The matching circuit was designed using CPW transmission lines. The open stubs and transmission lines were used for matching circuits of input/output and the interstage. Also, the W-band MMIC amplifier was designed as a low Q-factor matching circuit structure to improve the broadband characteristic. The bias line was designed using $\lambda/4$ (at 100 GHz) short stub [24]. The initial designed W-band amplifier was

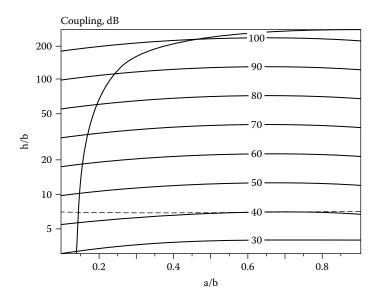


Figure 1.25 Constant-coupling curves for parallel coplanar lines on infinitely thick GaAs substrate ($\varepsilon_r = 13$) as a function of the shape ratio, a/b, and the normalized distance, D/b (log scale). (Taken from [23] IEEE 1987.)

optimized by the EM simulator (ADS MomentumTM). When EM simulation was performed, only the critical area was optimized without total pattern simulation. Therefore, reduction of simulation time and efficient design are possible. Figure 1.28 shows comparison data of circuit-based simulation and EM simulation for the pattern in Figure 1.27. From analysis results, an

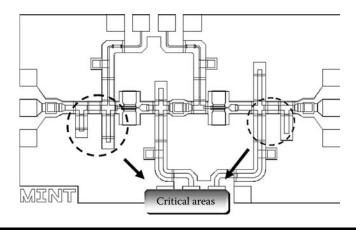


Figure 1.26 The preliminary layout of a W-band amplifier and critical areas.

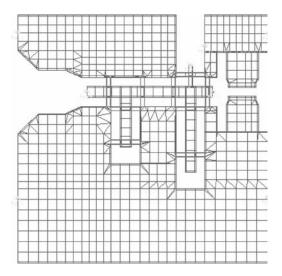


Figure 1.27 EM simulation pattern for critical areas.

apparent difference between circuit-based simulation and EM simulation of critical areas was obtained. The EM simulation exhibited higher impedance characteristics than circuit-based simulation (ideal case) due to parasitic effect (finite ground, line-to-line coupling). After the critical area was optimized, the completed amplifier circuit is shown in Figure 1.29. From the measured results, W-band MMIC amplifiers exhibit a broadband characteristic from the S21 gains of 11 ± 2 dB in a W-band frequency range of

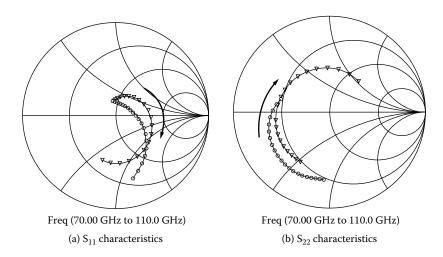


Figure 1.28 Comparison data of circuit-based simulation and EM simulation for critical areas (o: circuit-based simulation, ∇ : EM simulation).

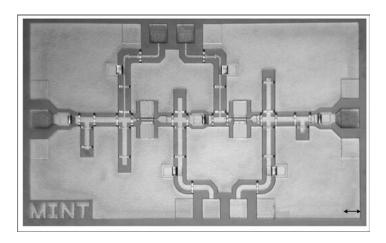


Figure 1.29 The fabricated MMIC W-band amplifier circuit (Millimeter-wave INnovation Technology Research Center (MINT) size: $1.8 \times 1.0 \text{ mm}^2$. (Taken from [24] IEEE 2004.)

70–100 GHz with good return losses. Also, a good agreement was obtained with the S-parameter measurements over the entire frequency range from 70 to 100 GHz compared to the simulated data. As shown in Figure 1.30, this result demonstrates that the presented design technology is a reasonable and efficient method in millimeter-wave ranges.

1.3.3 Millimeter-Wave Monolithic Integrated Circuit for WLAN

1.3.3.1 60-GHz Band MMIC Amplifier and Oscillator

Amplifiers are the basic building block of a wireless LAN system and mainly perform an amplification of weak signal. Amplifiers can be classified as low noise, drive, power, and linear. Also, HEMT and HBT devices have been generally adopted for MMIC amplifiers of millimeter-wave WLAN and so on. Figure 1.31 shows the performance of the reported 60-GHz MMIC lownoise amplifier and power amplifier for millimeter-wave WLAN [25–37]. A low-noise amplifier shows an S21 gain of 14–22.8 dB and a noise figure of 2.2–5.8 dB in a frequency range of 58–62 GHz, respectively. In the case of the MMIC power amplifier, an S21 gain of 7.5–13.8 dB and output power of 23–26.8 dBm were reported. A V-band MMIC low noise amplifier chip for millimeter-wave WLAN is shown in Figure 1.32. The MMIC low-noise amplifier is a three-stage circuit structure and GaAs PHEMTs are used. Circuit performances show an S21 gain of a typical 20 dB and a noise figure of 4.2 dB in the 55–65 GHz frequency range. The measured results of

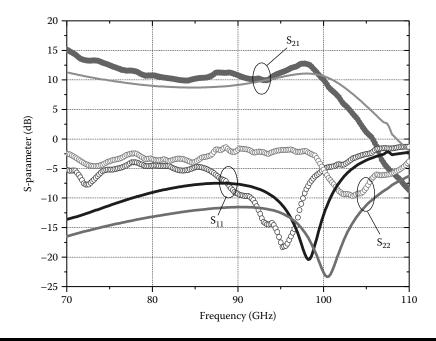


Figure 1.30 The simulated and measured results of the MMIC W-band amplifier circuit (o: measured data; —: simulated data). (Taken from [24] IEEE 2004.)

an MMIC low-noise amplifier are shown in Figure 1.33. This MMIC circuit can be used for the amplification block of a receiver in millimeter-wave WLAN, Oscillators are an essential block for millimeter-wave WLAN, Oscillators generate a millimeter-wave signal source using negative resistance. An ideal oscillator produces a pure sinusoidal carrier with fixed amplitude, frequency, and phase. Practical oscillators, however, generate carrier waveforms with parameters (oscillation frequency, output power) that may vary in time due to temperature changes and component characteristics. This phenomenon appears as phase and amplitude fluctuations at the oscillator output and will be of main concern in a wireless LAN system. Phase noise generation by the local oscillator at the receiver can significantly affect the performance of a wireless system. Figure 1.34 shows performance of the reported 60-GHz MMIC oscillator for millimeter-wave WLAN [38-41]. Oscillators show phase noise of -80 to -104 dBc/Hz and output power of 2.5–11.1 dBm in a frequency range of 56–62.5 GHz, respectively. Figure 1.35 is a photograph of the 60-GHz MMIC voltage-controlled oscillator (VCO), which was designed using GaAs PHEMTs. The VCO structure adopted an injection-locked VCO structure. CPW transmission lines and intrinsic gate capacitance of the HEMT are used for resonance at 60 GHz. To adjust the output frequency, a varactor diode of 280 width HEMT is used. A CPW

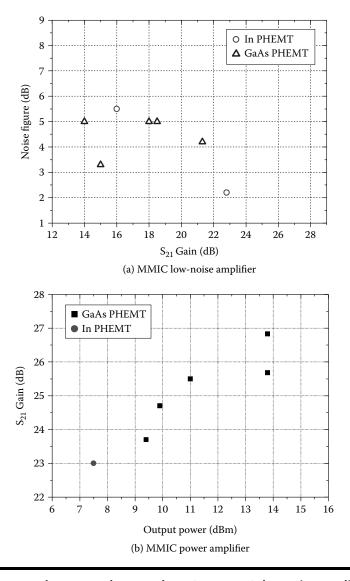


Figure 1.31 Performance of reported 60-GHz MMIC low-noise amplifier and power amplifier for millimeter-wave WLAN [25–37].

coupler is designed to inject the reference signal. The output phase of VCO is locked by the injected signal through the coupler. The major purpose of the buffer amplifier is to ensure proper matching of the oscillator output and isolation to the output port of VCO. Circuit performances show output power of typically 2.5 dBm and phase noise of 83 dBc/Hz (at 1 MHz offset) at 60 GHz oscillation frequency.

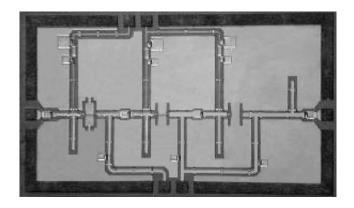


Figure 1.32 V-band MMIC low-noise amplifier for millimeter-wave wireless LAN (Millimeter-wave INnovation Technology Research Center (MINT); size: $2.6 \times 1.5 \mu m^2$) [25].

1.3.3.2 60-GHz Band MMIC Mixer

A mixer, or frequency converter, has the prime function of converting a signal from one frequency to another with minimum loss of the signal and minimum noise performance degradation. A mixer is one of the fundamental blocks of a wireless LAN system. A mixer faithfully preserves the amplitude and phase properties of the RF signal at the input. Therefore, signals can be translated into frequency without affecting their modulation properties. An ideal mixer multiplies the input signal by the sinusoidal signal generated by a local oscillator. This results in a mixed product that consists of higher and lower frequency components. Devices that exhibit

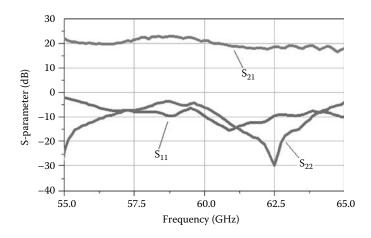


Figure 1.33 The measured results of a V-band MMIC low-noise amplifier [25].

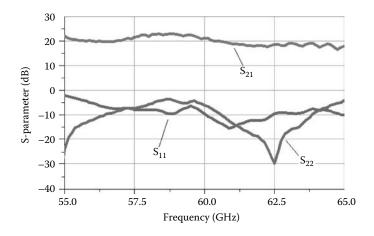


Figure 1.34 Performance of reported 60-GHz MMIC oscillator for millimeter-wave WLAN [38–41].

nonlinear or rectifying characteristics are good candidates for designing mixers. Diodes and HEMT devices are commonly used in the design of millimeter-wave mixers, because of their rectifying and nonlinear characteristics. Schottky barrier diodes have broad bandwidth and are low cost. Besides, diodes do not need DC bias to operate and have fast switching capability. On the other hand, HEMT or HBT devices have lower noise, better frequency response, and increased power handling ability. Also, HEMT and HBT devices are amenable to monolithic circuit integration. The

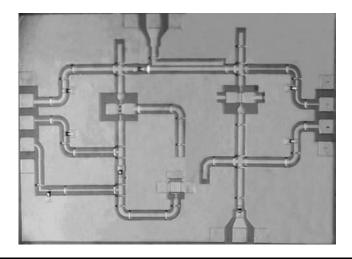


Figure 1.35 The 60-GHz MMIC voltage control oscillator (Millimeter-wave INnovation Technology Research Center (MINT); size: $2.2 \times 1.6 \ \mu m^2$).

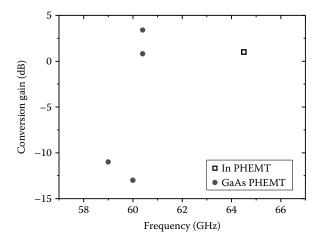


Figure 1.36 Performance of the reported 60-GHz MMIC mixer for millimeter-wave WLAN [42–46].

distortion caused by the inherent nonlinearities of the diodes is reduced in HEMT mixers. Figure 1.36 shows the performance of the reported 60-GHz MMIC mixer for a wireless LAN [42–46]. Conversion gains exhibit -13 to 3.4 dB in the frequency range of 59–64.5 GHz. Circuit structures have been studied in a single-ended diode mixer, balanced HEMT mixer, and balanced resistive mixer. A 60-GHz MMIC mixer chip for a millimeter-wave wireless LAN is shown in Figure 1.37. A circuit structure is a double-balanced

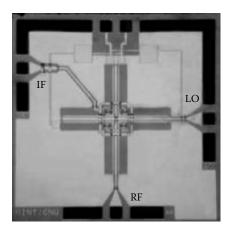


Figure 1.37 A 60-GHz MMIC mixer chip for millimeter-wave wireless LAN (Millimeter-wave INnovation Technology Research Center (MINT); size: $1.5 \times 1.5 \text{ mm}^2$. (Taken from [45] IEEE 2005.)

star mixer and GaAs PHEMT is used. The novel star mixer is composed of gate-drain (GD)-connected PHEMT diodes where the gate-source junctions are reverse biased to pinch off. Due to the reverse bias, the mixing occurs mainly by the DS conductance rather than by the gate-source junction diode. Consequently, the conversion loss does not suffer degradation due to the hetero-junction diode. Besides, the DS conductance is not as highly nonlinear as the diode point of the structure; the star mixer has a simpler topology, whereas the resistive ring mixer requires three separate baluns. More wideband operation is possible with the removal of the IF (intermediate frequency) balun [45]. Circuit performances show conversion loss of a typical 13 dB and isolation of a 35 dB at all ports. This circuit can be used for up/down frequency converters in the millimeter-wave WLAN. Furthermore, a subharmonic mixer has been researched in millimeter-wave ranges because a stable local oscillator (LO) signal is indispensable to the mixers. However, it is practically difficult to fabricate a stable oscillator operating at 60 GHz or above. Thus, continuous research and development efforts on the subharmonic mixers have been made because they can utilize lower LO frequencies than the conventional mixers [47]. This approach allows the use of a local oscillator of a relatively low frequency because an LO frequency is located at some integer fraction (1/n) of the fundamental LO frequency. For this reason, the subharmonic mixers with antiparallel diode structure were evaluated at millimeter-wave frequencies [48]. Figure 1.38 shows the designed circuit schematic of the 60-GHz MMIC subharmonic mixer. In this

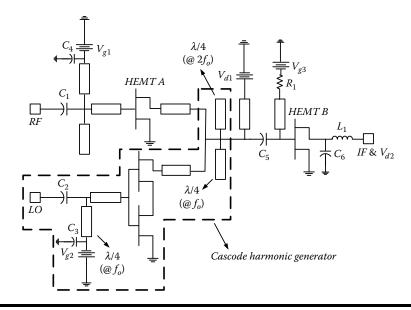


Figure 1.38 Circuit schematic of the 60-GHz MMIC subharmonic mixer. (Taken from [43] IEEE 2003.)

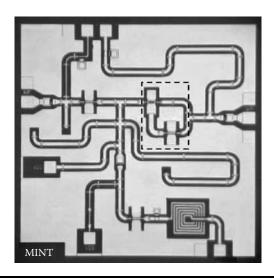


Figure 1.39 Micrograph of the fabricated MMIC subharmonic mixer (Millimeterwave INnovation Technology Research Center (MINT); size: $1.9 \times 1.8 \text{ mm}^2$; 2003 IEEE International Microwave Symposium; the cascode pair is shown in the dashed lines). (Taken from [43] IEEE 2003.)

work, a cascode harmonic generator is proposed to improve the conversion gain of the quadruple subharmonic mixer. The circuit of the subharmonic mixer was designed using the architecture of a gate mixer. An IF stage device (HEMT B) mixes the generated fourth harmonic signal and the RF signal. An RF stage device (HEMT A) not only amplifies the RF signal but also improves the LO-RF isolation due to the isolation characteristics of reverse direction. Matching circuits for the RF and the LO ports were designed using the CPW transmission lines. Figure 1.39 is a micrograph of the fabricated subharmonic mixer [43]. The measured results of the subharmonic mixer demonstrated that the conversion gain is 3.4 dB, which is a good conversion gain at the LO power of 13 dBm, as shown in Figure 1.40. Also, the conversion gain versus the LO input power was measured. The conversion gain is saturated at an LO input power level higher than 13 dBm, as shown in Figure 1.40. As shown in Figure 1.41, the fabricated subharmonic mixers show a good LO-to-IF isolation of -53.6 dB and LO-to-RF isolation of -46.2 dB at 14.5 GHz, respectively. The measurement results exhibited a high degree of isolation characteristics. The MMIC subharmonic mixer circuit provides high performance through the proposed cascode harmonic generator, and the cost of a wireless LAN system can be reduced because of utilization of a lower LO frequency than a conventional mixer. In addition, Figure 1.42 shows the circuit schematic and planar view micrograph of the fabricated 94-GHz MMIC resistive mixer chip using metamorphic

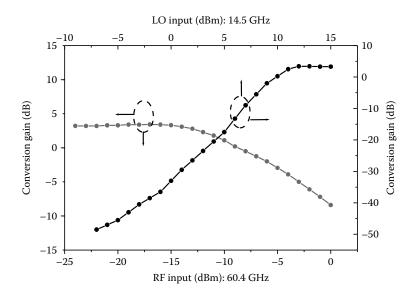


Figure 1.40 Conversion gain vs. RF input and LO input (RF frequency: 60.4 GHz; LO frequency: 14.5 GHz; IF frequency: 2.4 GHz). (Taken from [43] IEEE 2003.)

HEMTs [49]. Resistive mixers are widely used due to good conversion loss, low distortion, and no drain bias. Also, a frequency of 94 GHz has been actively researched as millimeter image sensor and FMCW (frequency modulated continuous wave) radar applications. However, the development of

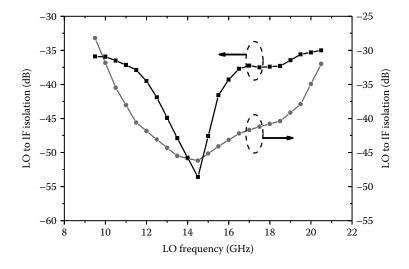


Figure 1.41 The measured results of isolation characteristics. (Taken from [43] IEEE 2003.)

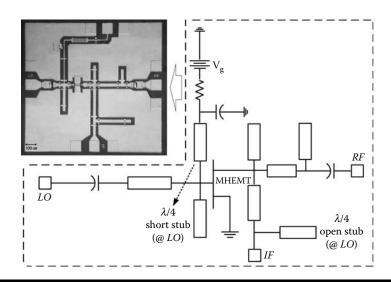


Figure 1.42 The circuit schematic and planar view micrograph of the fabricated 94-GHz MMIC resistive mixer (MINT), size: 1.2 \times 1.1 μ m². (Taken from [49] IEEE 2003.)

high-performance resistive mixers is difficult because of the limitations of the active device. Recently, GaAs-based metamorphic HEMTs (MHEMTs) adopted the low-cost GaAs substrates using the metamorphic buffers and higher indium mole fraction for the InGaAs channels than that of PHEMTs. Therefore, the MHEMTs materialize the same structure of InGaAs/InAlAs hetero-junction with the InP-based HEMTs and exhibit comparable RF performance for millimeter-wave applications [50]. The 94-GHz resistive mixer in this work was designed using MHEMTs for high performance. LO and RF matching circuits of the resistive mixer were implemented using coplanar waveguide transmission lines. A gate bias circuit was designed using a quarter-wavelength (4 at 94 GHz) short stub and a Ti thin-film resistor. A structure of a quarter-wavelength open stub was added at the IF stage for suppressing the LO signal at the IF port. The designed MMIC mixer was fabricated using the metamorphic HEMT-based MMIC process. Conversion loss of the mixer was measured with an applied RF signal of 94.075 GHz and an LO signal at 94.240 GHz. Conversion loss versus RF frequencies were obtained at an RF power of -20 dBm and LO power of 7 dBm. Figure 1.43 shows the simulated and measured conversion loss as a function of LO input power and RF frequencies. As shown in the plot, the resistive mixer exhibited a very low conversion loss of 8.2 dB at an LO power of 7 dBm. Compared to previously reported W-band (75–110 GHz) MMIC resistive mixers based on PHEMTs [51] or InP-based HEMTs [52], the MHEMT-based MMIC resistive mixer presented in this work has shown superior conversion loss.

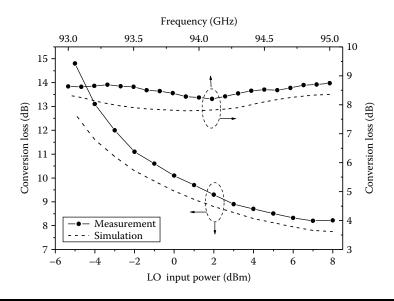


Figure 1.43 Conversion loss versus LO input power (at an LO frequency of 94.240 GHz, an RF frequency of 94.075 GHz, and an RF input power of -20 dBm) and RF frequencies (at an RF input power of -20 dBm and an LO input power of 7 dBm) measured for the MMIC resistive mixer. (Taken from [49] IEEE 2005.)

1.3.4 Fabrication Process of Millimeter-Wave Monolithic Integrated Circuits

There were few differences between the fabrication process for PHEMTbased MMICs and MHEMT-based MMICs, such as etching solution and metal thickness for ohmic contacts. However, a basic factor of fabrication is the same. In this chapter, we shall limit discussion of MHEMT-based MMICs. Fabrication processes for the MMIC were performed in the following sequence. First, mesa etching was done by the phosphoric acid-based etching solution. AuGe/Ni/Au for ohmic contacts were evaporated and annealed. After Ti metal evaporating for thin-film resistor, a 100-nm T-gate was patterned through a triple-layer resist pattern using electron beam lithography technology. Then, we performed a gate recess etching to control current of the devices. After the gate metal formation of Ti/Au, we performed the firstlevel metallization. And then, we deposited Si3N4 film for the passivation of MHEMTs and interlayer dielectric of the MIM (metal-insulator-metal) capacitor. After the RIE (reactive ion etching) process for opening the contact window, we finally performed the airbridge (second-level metallization) in order to connect between isolated electrodes.